# Preface

PV580 special inverters are developed for power supply of water pumps, based on the core control arithmetic of FR500 vector control inverters, combined with the control requirements of PV water pump application. The function of maximum power tracking, dormant at weak light, wake up at strong light, high water level dormant, under-load pre-warning and other control protection functions can ensure normal operation of water pumps according to the customers' requirements to switch to the grid power supply.

Please refer to this manual to commission the inverter, product maintenance refer to FR500 user manual.

**IMPORTANT NOTES**

◆To illustrate the details of the products，pictures in this manual based on products with outer casing or safety cover being removed. When using this product, please be sure to well install outer casing or covering by the rules, and operating in accordance with the manual contents.

◆The illustrations in this manual are for illustration only and may vary with different products you have ordered.

◆The company is committed to continuous improvement of products, product features will continue to upgrade, the information provided is subject to change without notice.

◆If there is any questions when using, please contact our regional agents or our customer service center:(+86-0755-88605930)

◆For other products, please visit our website. http://www.frecon.com.cn

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# Chapter 1 Product Overview

## 1.1 Name Plate

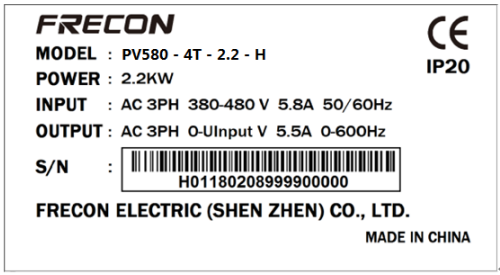



**Figure 1-1 Name Plate**

**Model Instruction**

Model numbers on name plate consist of numbers, symbols, and letters, to express its respective series, suitable power type, power level and other information.

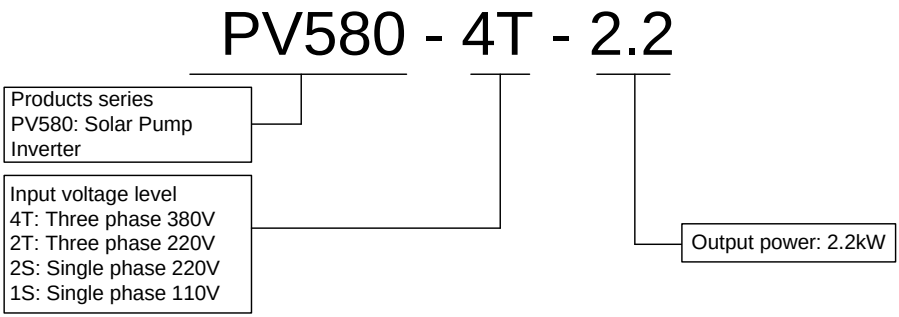



**Figure 1-2 Product Model Naming Rules**

## 1.2 Product Specifications

### 1.2.1 Electric specification of AC220 Input product

**Table 1-1Electric specification of AC220 Input product**

| Model | Recommended Solar Power (kW) | Maximum Input DC Current (A) | Rated Input AC Current (A) | Rated Output Current (A) | Adaptive Motor (kW) |
|---|---|---|---|---|---|
| PV580-2S-0.4 | 0.6 | 15 | 6.5 | 4.2 | 0.4 |
| PV580-2S-0.7 | 1.0 | 15 | 9.3 | 7.5 | 0.75 |
| PV580-2S-1.5 | 2.0 | 30 | 15.7 | 10.5 | 1.5 |
| PV580-2S-2.2 | 2.9 | 30 | 24 | 17 | 2.2 |

| **Input specification** | |
|---|---|
| **PV Input** | |
| Maximum Input DC Voltage | 450VDC |
| Recommended Voc Range | 360～430VDC |
| Recommended MPPT Voltage Range | 100～400VDC |
| Starting Voltage Range | 60～450VDC |
| **Grid or backup generator input** | |
| Input voltage | 200-260VAC (1PH) |
| **Output specification** | |
| Rated output voltage | 220V/230VAC(1PH or 3PH) |
| Output frequency | 0-50/60Hz |
| **Protection** | |
| Built-in Protection | Lighting Protection, over-current, overvoltage, output phase-lose, under-load, under-voltage, short circuit, overheating, water pump run dry etc. |

### 1.2.2 Electric specification of AC 380V&DC 540V Input product

**Table 1-2 Electric specification of AC 380V&DC 540V Input product**

| Model | Recommended Solar Power (kW) | Maximum Input DC Current (A) | Rated Input AC Current (A) | Rated Output Current (A) | Adaptive Motor (kW) |
|---|---|---|---|---|---|
| PV580-4T-2.2 | 2.9 | 15 | 5.8 | 5.5 | 2.2 |
| PV580-4T-4.0 | 5.2 | 15 | 11 | 9.5 | 4 |
| PV580-4T-5.5 | 7.2 | 30 | 14.6 | 13 | 5.5 |
| PV580-4T-7.5 | 9.8 | 30 | 20.5 | 17 | 7.5 |
| PV580-4T-011 | 14.3 | 37 | 26 | 25 | 11 |
| PV580-4T-015 | 19.5 | 48 | 35 | 32 | 15 |
| PV580-4T-018 | 24.1 | 55 | 38.5 | 37 | 18.5 |
| PV580-4T-022 | 28.6 | 67 | 46.5 | 45 | 22 |
| PV580-4T-030 | 39.0 | 90 | 62 | 60 | 30 |
| PV580-4T-037 | 48.1 | 112 | 76 | 75 | 37 |
| PV580-4T-045 | 58.5 | 136 | 92 | 91 | 45 |
| PV580-4T-055 | 71.5 | 168 | 113 | 112 | 55 |

| **Input specification** | |
|---|---|
| **PV Input** | |
| Maximum Input DC Voltage | 900VDC |
| Recommended Voc Range | 600～850VDC |
| Recommended MPPT Voltage Range | 450～850VDC |
| Starting Voltage Range | 230～900VDC |
| **Grid or backup generator input** | |
| Input Voltage | 360-460VAC (3PH) |
| **Output specification** | |
| Rated output voltage | 380-460VAC (3PH) |
| Output frequency | 0-50/60Hz |

| Protection | |
|---|---|
| Built-in Protection | Lighting Protection, over-current, overvoltage, output phase-lose, under-load, under-voltage, short circuit, overheating, water pump run dry etc. |
| **General Parameters** | |
| Application Site | No direct sunshine, no dust、corrosive gas、combustible gas、oil mist、steam、dripping or salinity etc. |
| Altitude | 0～3000 m<br>Derated use above 3000m,per 100m, the rated output current decrease 1%. |
| Environment Temperature | -25℃～60℃ (Above 60℃, derate the rated current capacity by 1% for every 1℃.) |
| Humidity | 5～95%,non-condensation |
| Vibration | less than 5.9 $m/s^2$（0.6g） |
| Storage Temperature | -20℃～+70℃ |
| Efficiency | Rated Power Run≥93% |
| Installation | Wall or rail mounting |
| Protection Grade | IP65 |
| Cooling | Natural cooling |

## 1.3 Product appearance

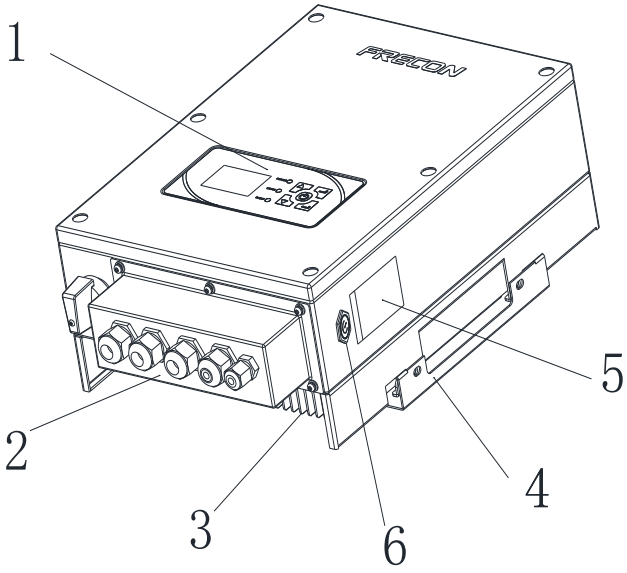



**Figure 1-3 Product outline**

| SN. | Name | Description |
|---|---|---|
| 1 | LCD Pad | Man-machine interface, used to monitor inverter status and related parameters, as well as parameter modification。 |
| 2 | Junction box | Contains the main circuit terminal and the control circuit terminal。 |
| 3 | Radiator | The main heat dissipation device of the machine, the temperature is high when the machine is running, please do not touch it. |
| 4 | Mounting plate | Mounting plate is used to fix drive on the wall |
| 5 | Machine nameplate | Contains the basic rated parameters of the machine for type selection。 |
| 6 | Start button | Used to start or stop drive |

## 1.4 Dimension Drawing

### 1.4.1 PV580

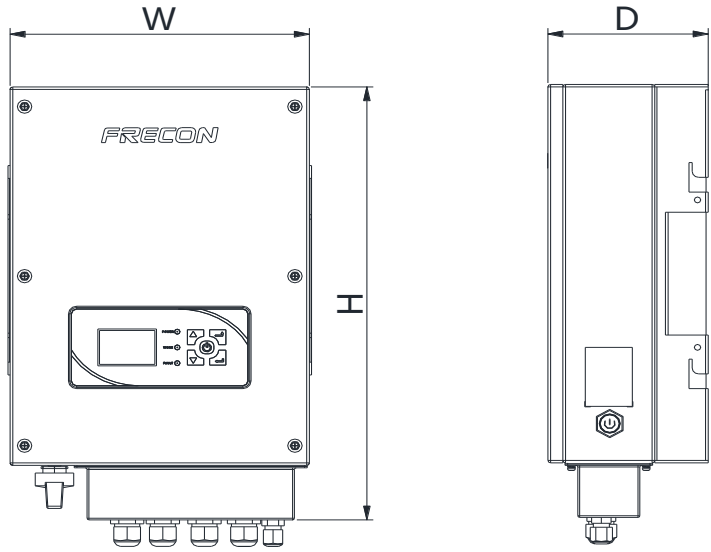



**Figure 1-4 Product dimensions**

Table1-4 **Configuration, mounting dimensions and weight**

| Model | External and installation dimensions (mm) | | | N.W (kg) |
|---|---|---|---|---|
| | W | H | D | |
| PV580-2S-0.4B | 280 | 440 | 150 | 11.4 |
| PV580-2S-0.7B | | | | |
| PV580-2S-1.5B | | | | |
| PV580-2S-2.2B | | | | |
| PV580-4T-2.2B | | | | |
| PV580-4T-4.0B | | | | |
| PV580-4T-5.5B | | | | |
| PV580-4T-7.5B | | | | |
| PV580-4T-011B | 360 | 550 | 190 | |
| PV580-4T-015B | | | | |
| PV580-4T-018B | | | | |
| PV580-4T-022B | | | | |
| PV580-4T-030B | 405 | 585 | 250 | |
| PV580-4T-037B | | | | |
| PV580-4T-045B | | | | |
| PV580-4T-055B | | | | |

# Chapter 2 Product Installation

## 2.1 Installation Environment Requirements

The environment of the inverter installation site has a very important impact on the safe operation, performance and life of the inverter.

Before installing the inverter, you need to choose the appropriate installation site.

1) All installations must comply with local installation standards.
2) Do not install the inverter in flammable or explosive places or storage places of flammable or explosive materials.
3) Do not install the inverter in a place where there is explosive danger.
4) Do not install the inverter where it is likely to be struck by lightning.
5) Do not install the inverter in a place with more salt fog.
6) Inverter installation site, it is necessary to ensure good ventilation, do not install the inverter in a closed box, otherwise the inverter will not work properly.
7) The inverter with protection grade IP65 can be installed outdoors. When the inverter is installed outdoors, it should be installed under the eaves or other shaded places as far as possible to avoid direct sunlight and direct rain and snow.
8) when the inverter is installed indoors, it is necessary to stay away from the window to prevent lightning strike.
9) the selected installation site should be strong enough to support the weight of the inverter for a long time.
10) the installation site of the inverter should be clean, and the ambient temperature range should be kept in the range of-20 ℃ ~ + 70 ℃.
11) the relative humidity of the inverter installation site should not exceed 95%, and water vapor may corrode the inverter and damage the internal devices.
12) the inverter is installed in a place where it is easy to observe the data and maintain it.
13) do not install the inverter in the living area, the inverter will produce some noise during operation, which will affect daily life.

## 2.2 Installation Method

**step1: Install the mounting plate on the wall**

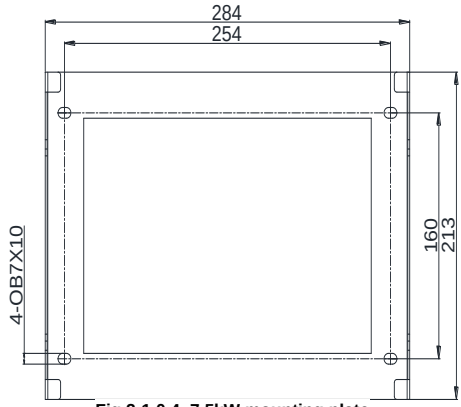



**Fig 2-1 0.4~7.5kW mounting plate**

**step2: Hang the drive on the mounting plate**

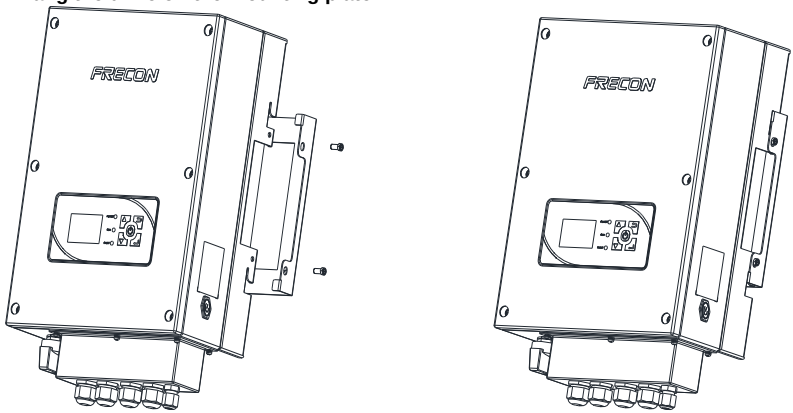



**Fig 2-2 Hang the drive on the mounting plate**

## 2.3 Installation Space Size

When installing, make sure that the machine has enough installation space. The following figure shows the minimum installation spacing:

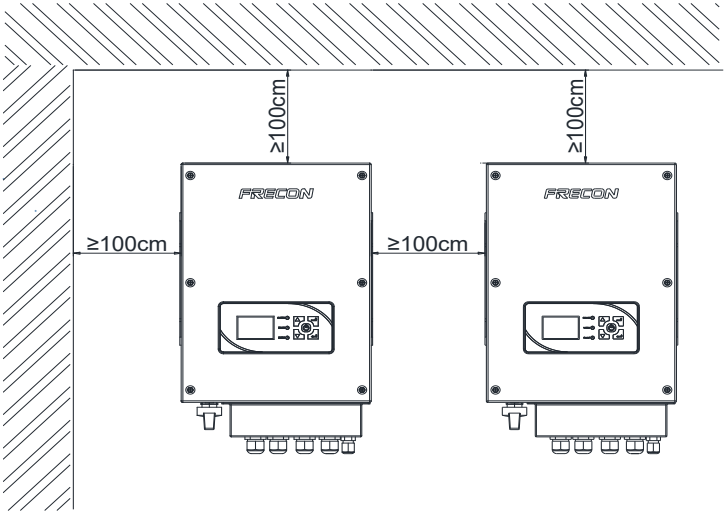



**Fig 2-3 Schematic diagram of installation space size**

## 2.4 Terminal Sescription

### 2.4.1 Main circuit terminal

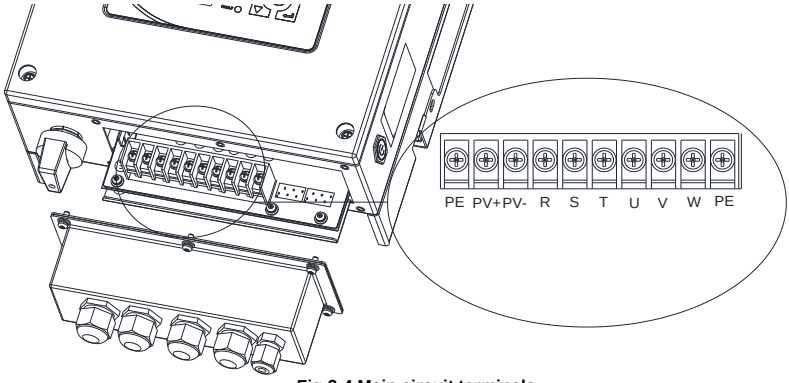



**Fig 2-4 Main circuit terminals**

| Terminals | Description |
|---|---|
| PV+, PV- | Solar power input terminals |
| R, S, T | AC power input terminals |
| U, V, W | AC output terminals |
| PE | Grounding terminal |

### 2.4.2 Control circuit terminal

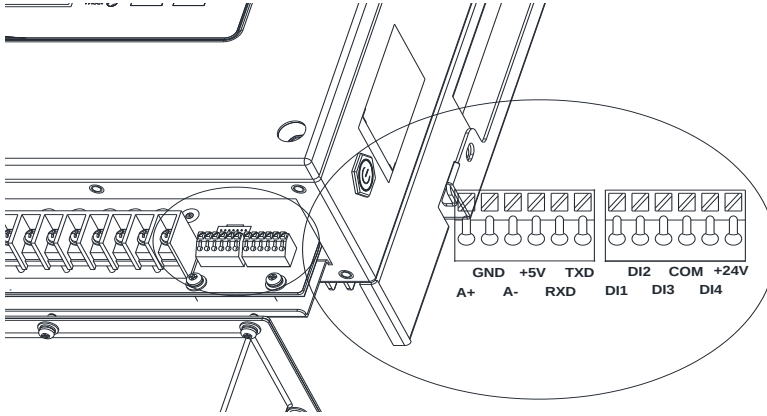



**Fig 2-5 Control circuit terminals**

**table2-1 Control circuit terminals**

| Type | Terminals | Name | Description |
|---|---|---|---|
| Power | +5V-GND | 5V Power | Provide + 5V power supply to the outside, maximum output current: 10mA. It is generally used as the working power supply of the external potentiometer, and the resistance range of the potentiometer is 1mm 5k Ω. |
| | +24V-COM | 24V Power | Provide + 24V power supply to the outside generally used as digital input and output terminal working power supply and external sensor power supply, maximum output current: 200mA |
| Digital input terminals | DI1-COM | Digital input terminal 1 | Maximum input frequency: 200Hz. Input impedance: 2.4k Ω. Voltage range when level input: 9V~30V |
| | DI2-COM | Digital input terminal 2 | |
| | DI3-COM | Digital input terminal 3 | |
| | DI4-COM | Digital input terminal 4 | |
| Communication terminals | A+，A- | RS485 Communication terminal | Speed: 4800/9600/19200/38400/57600/115200bps |
| | RXD,TXD | TTL Communication terminal | |

## 2.5 Electrical Connection

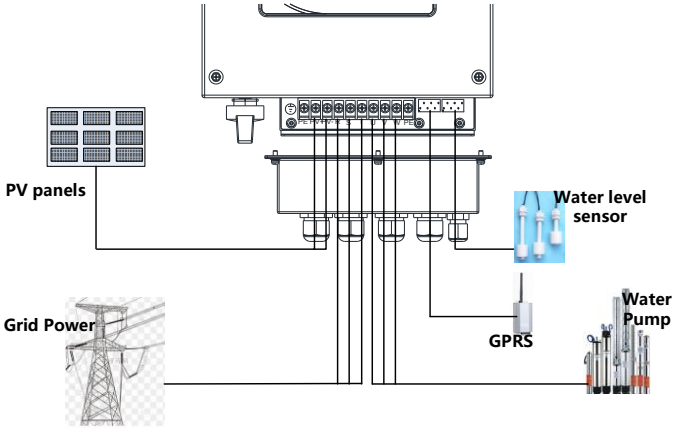
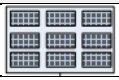



**Fig 2-4 Schematic diagram of electrical connection**

**Table 2-2 Peripheral device description**

| Picture | Name | Description |
|---|---|---|
|  | Solar Power | Provide DC power to the frequency converter, be careful not to exceed the DC maximum input point |
|  | Grid | Provide single-phase or three-phase AC AC power supply |
|  | Water pump | Single-phase or three-phase AC pump |
|  | Water level sensor | Used to detect water level |
|  | GPRS module | Used for remote monitoring of frequency converter |

# Chapter 3 LCD Operation And Display Instruction

## 3.1 LCD panel description

There are 3 indicator lights and 4 buttons on the LCD panel, as shown in the figure below:

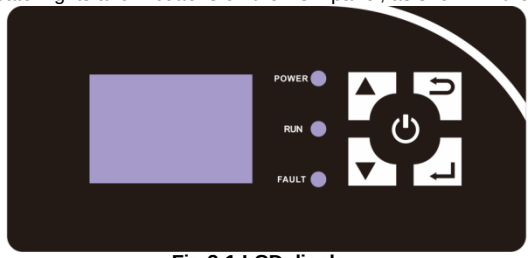



**Fig 3-1 LCD display**

### 3.1.1 Description of LED indicator

| LED | Name | Color | Description |
|---|---|---|---|
| POWER | Power indicator | green | ON: Power on<br>OFF: Power off |
| RUN | Running indicator | green | ON: Running<br>OFF: Power off<br>FLASH: Ramp to stop |
| FAULT | Error indicator | red | ON: Error<br>OFF: No Error<br>FLASH: Alarm |

### 3.1.2 Key Description

| Key | Key Name | Description |
|---|---|---|
| ▲ | "UP" key | Short press(less than 0.5s): Scroll up / Select the previous row / decrease the value;<br>Long press(more than 0.5s):left shift "<<" KEY |
| ▼ | "DOWN" key | Short press(less than 0.5s): Scroll down /select the next line / Increase the value<br>Long press(more than 0.5s): right shift ">>" KEY |
| ⏻ | "Start/Stop/ Reset" key | Start drive / stop drive / reset drive when error |
| ↩ | "ESC" Key | Enter into parameters menu / Return to the previous menu /Cancel parameter modification |
| ↵ | "ENT" Key | Enter into LCD function menu / enter into the next menu /Confirm parameter modification |

## 3.2 LCD Keyboard operation process

### 3.2.1 LCD Description of display interface

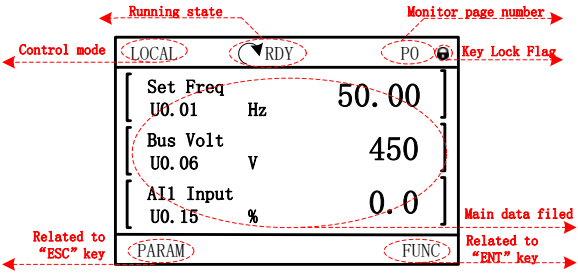



**Fig 3-2 LCD interface description**

| Field Name | Description |
|---|---|
| Control mode | "LOCAL" : drive is controlled by keypad<br>"REMOTE": drive is controlled by terminals<br>"PC": drive is controlled by communication |
| Running state | "RDY": drive is ready to run<br>"RUN": drive is running<br>"STOP": drive is ramp to stop<br>"ERR": drive is in error state<br>"ALARM": drive is alarm state |
| Monitor page number | P0 ~ P2(default), max is P4 |
| Main data filed | Show monitoring data or function parameters |
| Key Lock Flag | When F16.02 key lock function is enabled, key lock flag will show |

### 3.2.2 LCD Monitoring Pages

In the monitoring page, switch the display through "up" key / "down" key.

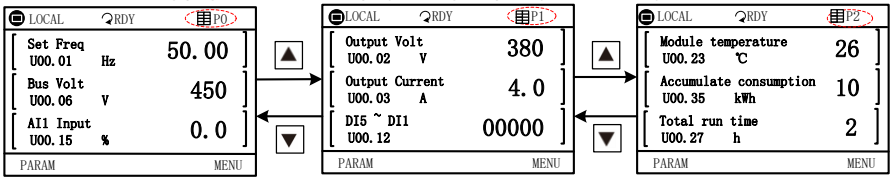



**Fig 3-3 Monitoring pages**

### 3.2.3 Parameters Modification

Eg：Set User password F00.00（00000->10000）

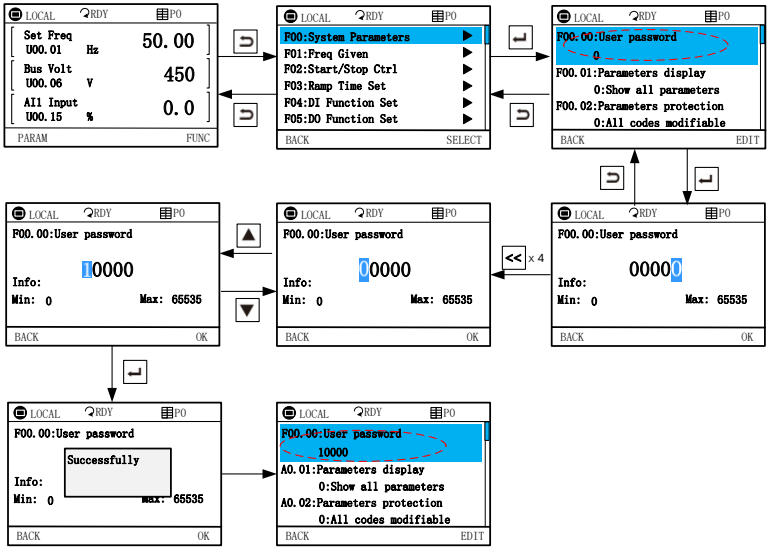



Fig 3-4 Example of parameters modification

### 3.2.4 Parameters backup

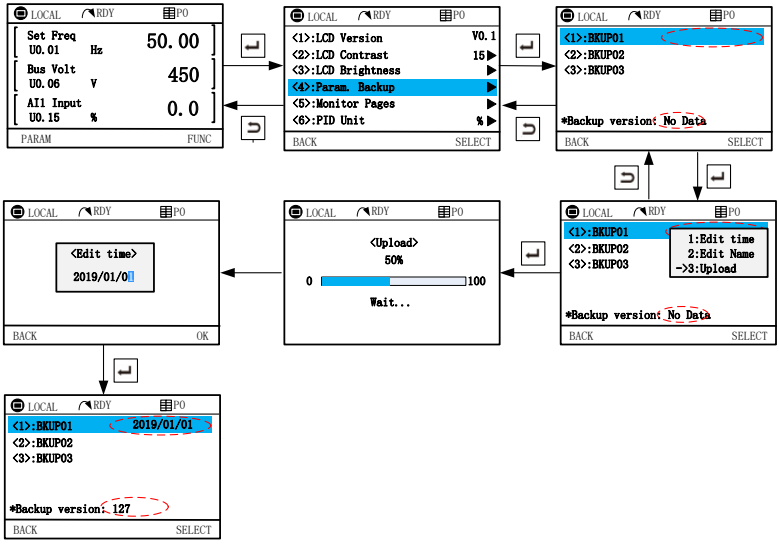



Fig 3-5 Example of parameters backup

### 3.2.4 Parameters restore

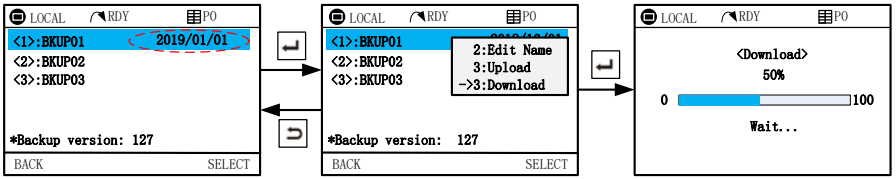
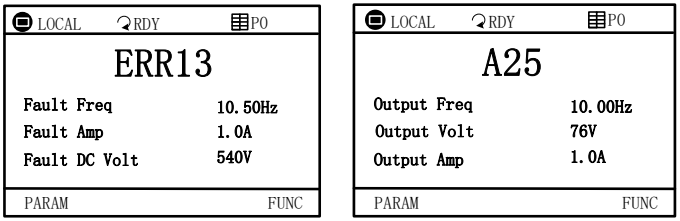



**Fig 3-6 Example of parameters restore**

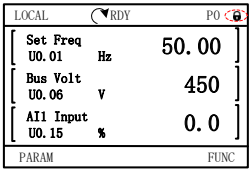
### 3.2.5 Error and Alarm Pages




### 3.2.6 Key lock function

1) Set a value that is not zero to F16.02.

2) Press "ESC + ENT" key at the same time to active key lock function. key lock flag show on Upper right corner.




3)Press "ESC + DOWN" key at the same time to unlock.

# Chapter 4 Commissioning Guide

## 4.1 PV Panel Power Supply Commissioning

1. Wiring drawings of below inverters shown as Figure 4-1: PV580 series.

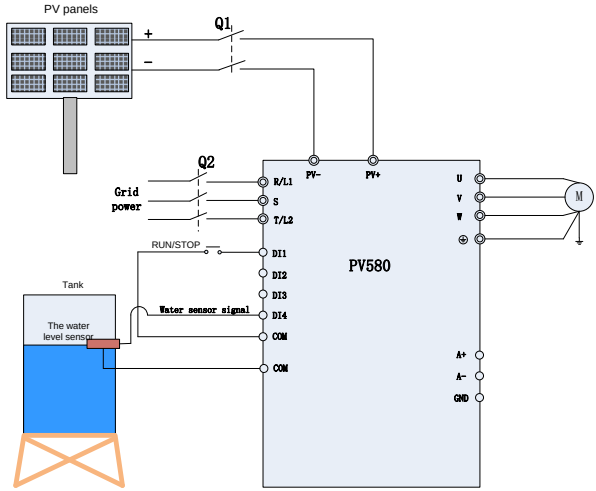



**Figure 4-1 PV580 Cell Power Supply Wiring Diagram**

**Step1**: Please wirings as Figure2-1, check and confirm the wirings to be correct (Q1 on, Q2 off)。

**Step2**: Setting the Motor Parameters

Setting the parameter of name plate on motor F08.01～F08.05。

**Step3**: Testing the water yield of pump

Press the operation key , under normal circumstance of light strength, if the operation frequency low or water yield less, which means the motor wiring may be reversed, please exchange two wirings of motor.

**Step4**: System Effluent Speed PI Regulating

If the user has a high requirements for the effluent speed, PI parameters can be regulated appropriately（H00.09～H00.10）, the larger PI parameter, the stronger affection, the faster effluent, but the larger fluctuation of motor frequency; Otherwise, the slower water effluent, the more steady frequency of motor operation.

**Step5:** . Setting of fault point and fault delay reset time

If clients need to use the pre-warning of weak light, water-logged, under-load, failure monitoring point, delay time and reset time, water-logged/controlled function can be set as H00.15~H00.19 on demand; under-load function set as H00.20~H00.22; weak light function set as H00.13~H00.14. Users also can adopt the default value.

**Step6:** . Parameter setting after the system operation normally

When the water yield is normal, and system run steadily, the commissioning will be finished. And then setting F02.00=1, change to terminal operation mode, setting failure auto reset times F11.27=5.

## 4.2 Grid or Generator power supply wirings

Wiring drawings of below inverters shown as below:

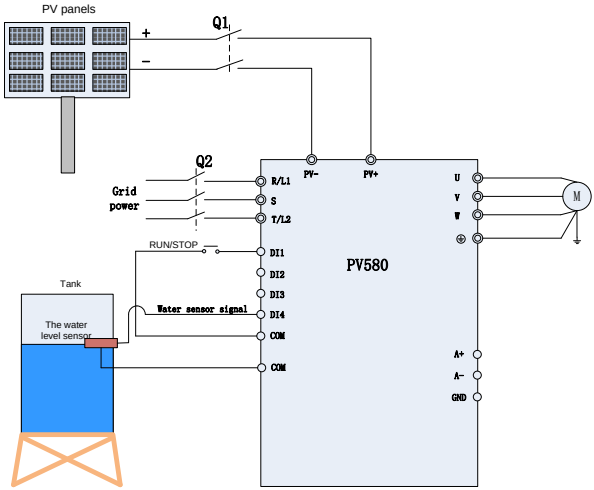



**Figure 4-2 PV580 Grid or Generator power supply wirings**

**Step1:** Wirings as Figure4-2system wiring drawings, check and confirm the connections to be correct.

**Step2:** Q2 on, Q1 off.

**Step3:** When grid or generator power supply, setting H00.01=0, power supplied by grid.For water

**Step4:** pump's frequency, please refer to F01 group code, H00.02~H00.12 function code does not work.

**Step5:** When change to PV power supply, setting F04.01=51 and close the terminal DI2 (or setting H00.01=1).

## 4.3 Grid and PV power supply wirings

PV580 allow Grid and PV input at the same time

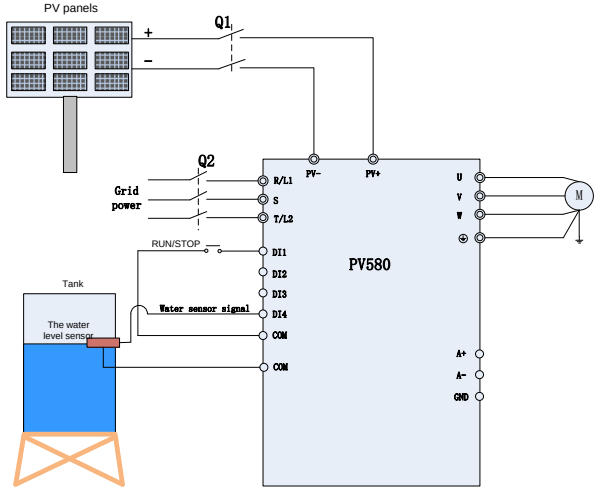



**Figure 4-3 gird and PV power supply wirings**

Close Q1 and Q2, PV580 will select the power that voltage is higher as current power supply automatically.

## 4.4 Wiring diagram for single phase motor

### 4.4.1 Single phase motor introduction

Single phase motor generally means asynchronous single phase motor powered by single phase AC 220V, there're two phase winding in motor stator and motor rotor is common squirrel cage. The distribution of two phase winding and different power supply will lead to different starting characteristics and operating characteristics

Usually single phase motor is with single capacitor or double capacitor, photos of motor are as below:

**Figure 4-4 Motor with single capacitor and double capacitor**

Single phase motor is consisted of main winding, secondary winding, capacitor and centrifugal switch, internal wiring of single phase motor with single capacitor is as below:

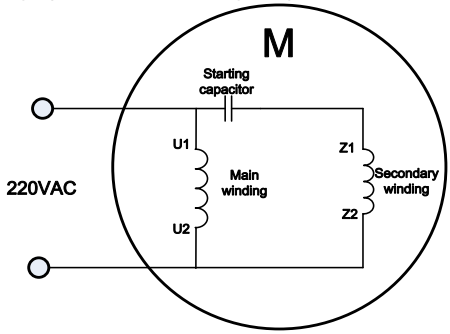



**Figure 4-5 Operation mode: Internal wiring of motor with single capacitor**

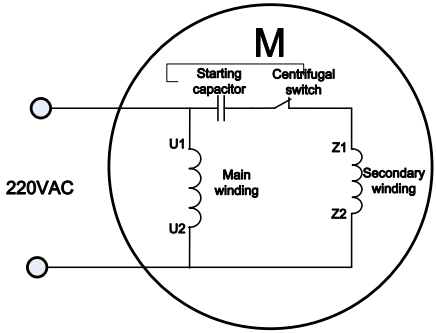



**Figure 4-6 Starting mode: Internal wiring of motor with single capacitor**

Internal wiring of single phase motor with double capacitors is as below:

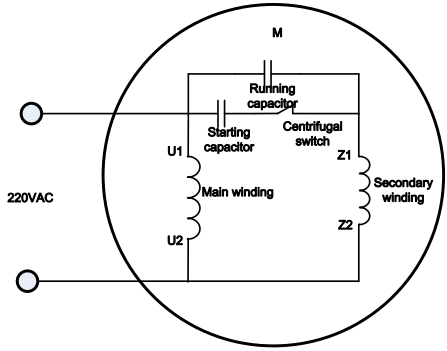



**Figure 4-7 Internal wiring of motor with double capacitors**

Resistor starting mode single phase motor, and internal wiring is as below:

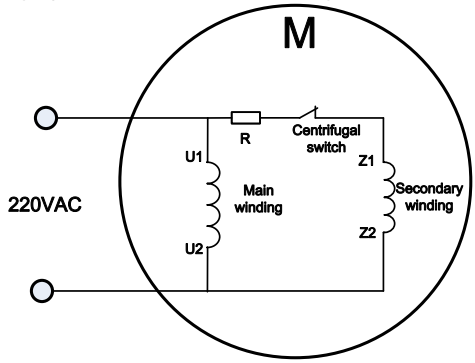



**Figure 4-8 Resistor starting mode: Internal wiring of motor**

We can remove capacitors from above motors, and remaining 4 main and secondary winding terminals as below:

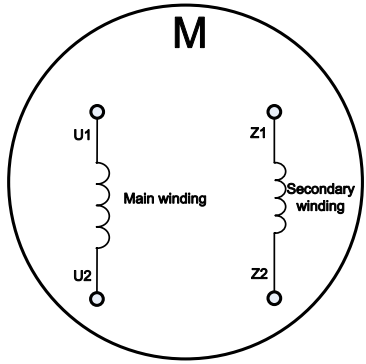



**Figure 4-9 Main and secondary winding of motor**

### 4.4.2 Wiring between VFD and motor（Capacitor removable）

Connect main and secondary winding of motor to inverter UVW, then inverter can work. But due to the motor winding difference, motor forward wiring must be as below, if not cause motor too heat

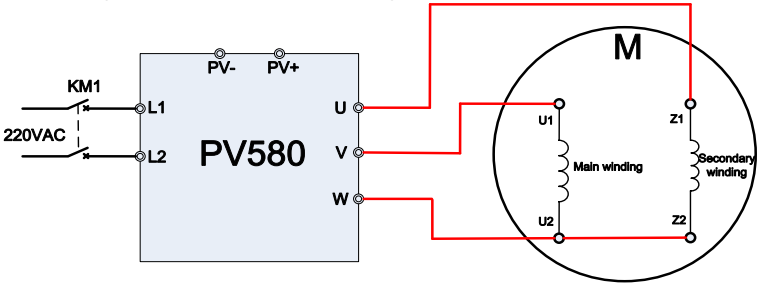



**Figure 4-10 Forward wiring between PV580 VFD and motor**

Motor reverse can't be completed through parameter setting of inverter or change any two phase wirings, motor reverse wiring must be as below:

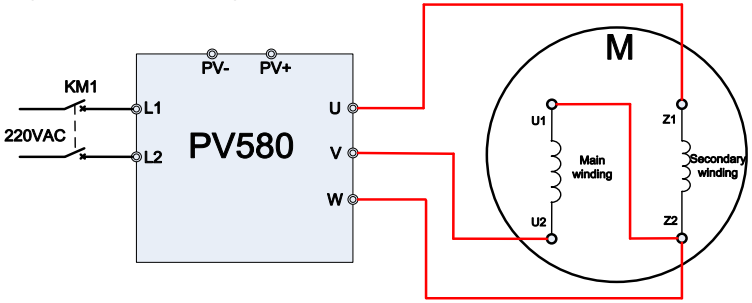



**Figure 4-11 Reverse wiring between PV580 VFD and motor**

**Note:** After wiring completed, need to set F08.00=2.

### 4.3.3 Wiring between VFD and motor（Capacitor is not removable）

If the capacitor in motor is not removable, the wiring is as below. The forward and reverse is determined by UV wiring sequence.

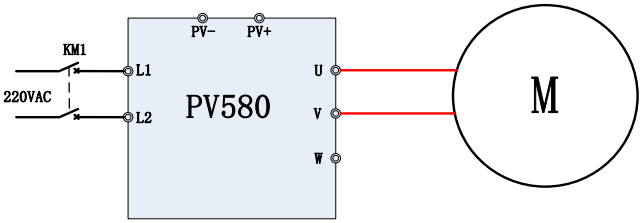



**Figure 4-12 Wiring between PV580 VFD and motor**

**Note:** After wiring completed, need to set F08.00=3

# Chapter 5 Function Parameters

## 5.1 The Basic Function Parameters

**Table 3-1 Basic Function Parameters**

| Param. | Parameter Name | Setting Range | Default | Attr |
|---|---|---|---|---|
| **Group F00: System Parameters** | | | | |
| F00.00 | Setting of User Password | 0～65535 | 0 | × |
| F00.01 | Display of Parameters | 0: Display all parameters<br>1: Only display F00.00, F00.01 and user-defined parameters F17.00～F17.29<br>2: Only display A0-00, A0-01, and the parameters different with factory default | 0 | × |
| F00.02 | Parameter Protection | 0: All parameter programmable<br>1: Only F00.02 and this parameter programmable | 0 | × |
| F00.03 | G/P type display | 0: G type (constant torque load)<br>1: P type (variable torque load e.g. fan and pump) | 0 | × |
| F00.04 | Parameter Initialization | 0: No operation<br>1: Restore all parameters to factory default (excluding motor parameters)<br>2: Clear fault record<br>3: Back up current user parameters<br>4: Restore user backup parameters<br>5: Restore factory default(include motor parameter)<br>6: Power consumption zero clearing(U00.35) | 0 | × |
| F00.05 | Copy of Parameters(Need an uploading and downloading module) | 0: No operation<br>1: Upload parameter<br>2: Download parameter (excluding motor parameters)<br>3: Download parameter (including motor parameters) | 0 | × |
| F00.06 | Parameter editing mode | 0:Editable via keypad and RS485<br>1:Editable via keypad<br>2:Editable via RS485 | 0 | × |
| F00.08 | Motor 1 control mode | 0: Voltage/Frequency (V/F) control<br>1:Sensor-less vector control 1<br>2: Sensor-less vector control 2 | 1 | × |
| F00.09 | DI7/HI input mode | 0:Digital input terminal 7<br>1: Pulse input | 0 | × |
| F00.10 | AI1\AI2\AI3 input mode | Unit's place: AI1<br>0: Analog input<br>1: Digital input<br>Decade: AI2 (same as AI1) | 000 | × |

| | | | | |
|---|---|---|---|---|
| | | Hundreds place: AI3 (same as AI1) | | |
| F00.11 | Y2/HO input mode | 0: Digital 0utput terminal 2<br>1: Pulse output | 0 | × |
| F00.12 | PWM optimization | Unit' place: PWM modulation mode<br>0: Fixed carrier<br>1: Random carrier<br>2: Derating of fixed carrier<br>3: Derating of random carrier<br>Ten' place: PWM modulation mode<br>0: Seven-segment mode<br>1: Five-segment mode<br>2: Five-segment and seven-segment automatic switchover<br>Hundred' place: over-modulation adjustment<br>0: Invalid<br>1~9: 1.01~1.09 times of over-modulation | 000 | × |
| F00.13 | Carrier frequency | 0.700～16.000kHz | Model defined | △ |
| F00.14 | Upper carrier frequency | 0.700～16.000kHz | 8.000kHz | × |
| F00.15 | Lower carrier frequency | 0.700～16.000kHz | 2.000kHz | × |
| F00.16 | Output voltage | 5.0～150.0% | 100.0% | × |
| F00.17 | AVR | 0: Disabled<br>1: Enabled<br>2: AVR is disabled if the DC bus voltage > the rated voltage of DC bus, and it will be enabled if the DC bus voltage≤the rated voltage of DC bus. | 1 | × |
| F00.18 | Fan control | 0: Run at power-on<br>1: Fan working during running | 1 | × |
| F00.19 | Factory password | 0～65535 | 0 | × |
| F00.20 | Inverter rated power | 0.2～710.0kW | Model defined | ⊙ |
| F00.21 | Inverter rated voltage | 60～660V | Model defined | ⊙ |
| F00.22 | Inverter rated current | 0.1～1500.0A | Model defined | ⊙ |
| F00.23 | Software version | 0.00～655.35 | Model defined | ⊙ |
| F00.24 | Dealer password | 0～65535 | 0 | × |
| F00.25 | Setting operation time | 0～65535h(0: Invaild) | 0h | × |
| **Group F01: Frequency Command** | | | | |
| F01.00 | Frequency source selection | 0: Master frequency source<br>1: Auxiliary frequency source<br>2: Master +Auxiliary<br>3: Master - Auxiliary<br>4: MAX{Master, Auxiliary }<br>5: MIN {Master, Auxiliary }<br>6: AI1( Master + Auxiliary)<br>7: AI2( Master +Auxiliary) | 0 | × |
| F01.01 | Master Frequency | 0:Master digital setting (F01.02) | 1 | × |

| | | | | |
|---|---|---|---|---|
| | Command Source | 1: keypad potentiometer<br>2: Analog input AI1<br>3: Communication<br>4: Multi-reference<br>5: PLC<br>6: Process PID output<br>7: X7/HI pulse input<br>8：AI2<br>9：AI3 | | |
| F01.02 | Digital Setting of Master Frequency | 0.00～Fmax | 50.00Hz | △ |
| F01.03 | Auxiliary Frequency Command Source | 0: Auxiliary digital setting (F01.04)<br>1: keypad potentiometer<br>2: Analog input AI1<br>3: Communication<br>4: Multi-reference<br>5: PLC<br>6: Process PID output<br>7: X7/HI pulse input<br>8: Analog input AI2<br>9: Analog input AI3 | 0 | × |
| F01.04 | Digital setting of auxiliary frequency | 0.00～Fmax | 50.00Hz | △ |
| F01.05 | Range of auxiliary frequency | 0: Relative to maximum frequency<br>1: Relative to master frequency | 0 | × |
| F01.06 | Coeff of auxiliary frequency | 0.0～150.0% | 100.0% | △ |
| F01.07 | Jog frequency | 0.00～Fmax | 5.00Hz | △ |
| F01.08 | Maximum frequency | 20.00～600.00Hz | 50.00Hz | × |
| F01.09 | Upper limit frequency | Fdown～Fmax<br>Lower limit frequency～maximum frequency | 50.00Hz | × |
| F01.10 | Lower limit frequency | 0.00～Fup | 0.00Hz | × |
| F01.11 | Operation when command frequency lower than lower limit frequency | 0: Run at lower limit frequency<br>1: Run at 0 Hz would be activated after the time delay set by F01.12 | 0 | × |
| F01.12 | Lower limit frequency running time | 0.0～6000.0s | 60.0s | × |
| F01.13 | Up to this frequency, start frequency compensation | 0.00~600.00Hz | 50.00Hz | △ |
| F01.14 | Frequency compensation per 50Hz | 0.00~50.00Hz | 0.00Hz | △ |
| **Group F02: Start/Stop Control** | | | | |
| F02.00 | Run command | 0: Keypad control (LED off)<br>1: Terminal control (LED on)<br>2: Communication control (LED blinking) | 0 | × |
| F02.01 | Running direction | 0: Forward<br>1: Reverse | 0 | △ |
| F02.02 | Reverse-proof action | 0: Reverse enabled<br>1: Reverse disabled | 0 | × |
| F02.03 | Dead time between forward and reverse | 0.0～6000.0s | 0.0s | × |
| F02.04 | Start mode | Unit's place: | 0000 | × |

| | | | | |
|---|---|---|---|---|
| | | 0:Start directly<br>1:Rotational speed track and restart | | |
| | | Ten's digit:<br>0:Ungrounded short-circuit detection<br>1:Grounding short-circuit detection before the first starts<br>2:Grounding short-circuit detection before each starts | | |
| | | Hundred's digit<br>0:Track from zero speed<br>1:Track from max frequency | | |
| | | Thousand's:Select if Jog function takes the priority<br>0:Disable<br>1:Enable | | |
| | | Ten thousand's place: speed tracking direction<br>0: last parking direction<br>1: forward<br>2: reverse<br>3: Starting direction | | |
| F02.05 | Start frequency | 0.00～10.00Hz | 0.00Hz | × |
| F02.06 | Startup frequency holding time | 0.0～100.0s | 0.0s | × |
| F02.07 | Startup DC brakin current | 0.0～150.0% | 0.0% | × |
| F02.08 | DC braking time at start | 0.0～100.0s | 0.0s | × |
| F02.09 | Speed search current | 0.0～180.0% | 130.0% | △ |
| F02.10 | Sped search decel time | 0.0～10.0s | 1.0s | × |
| F02.11 | Sped search coefficient | 0.01～5.00 | 0.30 | △ |
| F02.12 | Stop mode | 0: Ramp to stop<br>1: Coast to stop | 0 | × |
| F02.13 | Initial frequency of stop DC braking | 0.01～50.00Hz | 2.00Hz | × |
| F02.14 | Stop DC braking current | 0.0～150.0% | 0.0% | × |
| F02.15 | Waiting time of stop DC braking | 0.0～30.0s | 0.0s | × |
| F02.16 | Stop DC braking time | 0.0～30.0s | 0.0s | × |
| F02.17 | Dynamic brake | 0: Disabled<br>1: Enabled<br>2: Enabled at running<br>3: Enabled at deceleration | 0 | × |
| F02.18 | Voltage of dynamic braking | 480～800V | 700V | × |
| F02.19 | Brake use ratio | 5.0～100.0% | 100.0% | × |
| F02.20 | 0Hz output selection | 0: No voltage output<br>1: Voltage output | 0 | × |
| F02.21 | Auto-start of power-on again | 0: Invalid<br>1: Valid | 0 | △ |
| F02.22 | Waiting time between auto-start and power-on again | 0.0~10.0s | 0.5s | △ |
| **Group F03: Accel/Decel Parameters** | | | | |
| F03.00 | Accel time 1 | 0.0～6000.0s | 15.0s | △ |
| F03.01 | Decel time 1 | 0.0～6000.0s | 15.0s | △ |

| | | | | |
|---|---|---|---|---|
| F03.02 | Accel time 2 | 0.0～6000.0s | 15.0s | △ |
| F03.03 | Decel time 2 | 0.0～6000.0s | 15.0s | △ |
| F03.04 | Accel time 3 | 0.0～6000.0s | 15.0s | △ |
| F03.05 | Decel time 3 | 0.0～6000.0s | 15.0s | △ |
| F03.06 | Accel time 4 | 0.0～6000.0s | 15.0s | △ |
| F03.07 | Decel time 4 | 0.0～6000.0s | 15.0s | △ |
| F03.08 | Jog accel time | 0.0～6000.0s | 15.0s | △ |
| F03.09 | Jog decel time | 0.0～6000.0s | 15.0s | △ |
| F03.10 | Accel/Decele curve | 0: Linear Accel/Decel<br>1: S-curve Accel/Decel | 0 | × |
| F03.11 | Initial segment time of acceleration of S curve | 0.0～6000.0s | 0.0s | × |
| F03.12 | Time unit of acceleration and deceleration | 0: 0.1s<br>1: 0.01s | 0 | × |
| F03.13 | Frequency switchover point between acceleration time 1 and acceleration time 2 | 0.00～Fmax | 0.00Hz | × |
| F03.14 | Frequency switchover point between deceleration time 1 and deceleration time 2 | 0.00～Fmax | 0.00Hz | × |
| F03.15 | End segment time of acceleration of S curve | 0.0～6000.0s | 0.0s | × |
| F03.16 | Initial segment time of deceleration of S curve | 0.0～6000.0s | 0.0s | × |
| F03.17 | End segment time of deceleration of S curve | 0.0～6000.0s | 0.0s | × |
| **Group F04 Digital Input** | | | | |
| F04.00 | Function of terminal DI1 | 00: No function<br>01: Running forward (FWD)<br>02: Running reverse (REV)<br>03: Three-wire control<br>04: JOG forward<br>05: JOG reverse<br>06: Coast to stop<br>07: Fault reset (RESET)<br>08: Running suspended<br>09: External fault input<br>10: Terminal UP<br>11: Terminal DOWN<br>12: UP/DOWN (including ∧/∨ key) adjustment clear<br>13: Multi-step frequency terminal 1<br>14: Multi-step frequency terminal 2<br>15: Multi-step frequency terminal 3<br>16: Multi-step frequency terminal 4<br>17: Accel/Decel time determinant 1<br>18: Accel/Decel time determinant 1<br>19: Accel/Decel disabled(ramp stop not inclusive)<br>20: Switch to auxiliary speed setting<br>21: PLC status reset<br>22: Simple PLC paused | 1 | × |
| F04.01 | Function of terminal DI2 | | 2 | × |
| F04.02 | Function of terminal DI3 | | 7 | × |
| F04.03 | Function of terminal DI4 | | 13 | × |
| F04.04 | Function of terminal DI5 | | 0 | × |
| F04.05 | Function of terminal DI6 | | 0 | × |
| F04.06 | Function of terminal DI7 | | 0 | × |
| F04.07 | Function of terminal AI1 | | 0 | × |
| F04.08 | Function of terminal AI2 | | 0 | × |
| F04.09 | Function of terminal AI3 | | 0 | × |

| | | | | |
|---|---|---|---|---|
| | | 23: Simple PLC paused<br>24: PID adjustment direction<br>25: PID integration paused<br>26: PID parameter switch<br>27: Swing frequency pause(output the currentfrequency)<br>28: Swing frequency reset(output the central frequency)<br>29: Run command switched to keypad contro<br>30: Run command switched to terminal control<br>31: Run command switched to communication control<br>32: Count input<br>33: Count clear<br>34: Length count<br>35: Length clear<br>36: DC brake input command at Stop<br>37: Speed/torque control switch<br>38:No reverse<br>39:No forward<br>50: Special machine enable<br>51: Solar panel power supply enable<br>52: Enter into dormancy | | |
| F04.10 | Filtering time of digital input terminal | 0.000～1.000s | 0.010s | △ |
| F04.11 | Delay time before terminal DI1 is valid | 0.0～300.0s | 0.0s | △ |
| F04.12 | Delay time before terminal DI2 is valid | 0.0～300.0s | 0.0s | △ |
| F04.13 | Terminal DI1～DI5 positive/negative logic | DI5, DI4, DI3, DI2, DI1<br>0: Positive logic(Terminals are on at 0V/off at 24V)<br>1: Negative Logic (Terminals are off at 0V/on at 24V) | 00000 | × |
| F04.14 | Terminal DI6～AI3 positive/negative logic | AI3, AI2, AI1, DI7, DI6<br>0: Positive logic<br>1: Negative Logic | 00000 | × |
| F04.15 | FWD/REV terminal control mode | 0: Two-wire mode 1<br>1: Two-wire mode 2<br>2: Three-wire mode 1<br>3: Three-wire mode 2 | 0 | × |
| F04.16 | Terminal UP/DOWN frequency adjustment control | Unit's place: action when stop<br>0: Clear<br>1: Holding<br>Decade: action on power loss<br>0: Clear<br>1: Holding<br>Hundreds place: integral function<br>0: No integral function<br>1: Integral function enabled<br>Thousand's place：Select if it can be reduced to negative frequency<br>0: Disable<br>1: Enable | 00001 | × |

| | | | | |
|---|---|---|---|---|
| | | Ten thousand's place: Select if Jog action can clear UP/DOWN or not<br>0: Not zero-clearing<br>1: Zero-clearing | | |
| F04.17 | Terminal UP/DOWN frequency change step size | 0.00～50.00Hz 0.00:Disabled | 1.00Hz/ 200ms | △ |
| F04.18 | Terminal action selection when power on | 0: Level effective<br>1: Edge trigger +Level effective(When power on)<br>2: Edge trigger +Level effective(Every start) | 0 | × |
| F04.19 | Delay time before terminal DI1 is invalid | 0.0～300.0s | 0.0s | △ |
| F04.20 | Delay time before terminal DI2 is invalid | 0.0～300.0s | 0.0s | △ |
| **Group F05 Digital Output** | | | | |
| F05.00 | Y1 output function | 0: No output<br>1: Drive is running<br>2: Fault output<br>3: Frequency-level detection FDT1 output<br>4: Frequency-level detection FDT2 output<br>5: Drive in 0Hz running 1(no output at stop)<br>6: Drive in 0Hz running 2(output at stop)<br>7: Upper limit frequency attained<br>8: Lower limit frequency attained<br>9: Frequency attained<br>10: Inverter is ready to work<br>11: Drive (motor) overloaded alarm<br>12: Inverter overheat warning<br>13: Current running time attained<br>14: Accumulative power-on time attained<br>15: Consecutive running time attained<br>16: PLC cycle completed<br>17: Set count value attained<br>18: Designated count value attained<br>19: Length attained<br>20: Under load alarm<br>21:Brake output<br>22: DI1<br>23: DI2<br>24:When reach the range of set frequency(FDT1)<br>25:Reserved<br>26: PID feedback lost<br>27: operation status (inching without output)<br>28: communication setting (address 2007h)<br>30:Grid and solar power autoswitch | 1 | × |
| F05.01 | Y2 output function | | 3 | |
| F05.02 | Relay 1 output function | | 2 | × |
| F05.03 | Relay 2 output function | | 11 | × |
| F05.04 | Y1 output delay time | 0.0～6000.0s | 0.0s | △ |

| | | | | |
|---|---|---|---|---|
| F05.05 | Y2 output delay time | 0.0～6000.0s | 0.0s | △ |
| F05.06 | R1 output delay time | 0.0～6000.0s | 0.0s | △ |
| F05.07 | R2 output delay time | 0.0～6000.0s | 0.0s | △ |
| F05.08 | Enabled state of digital output | Unit's place: Y1<br>0: Positive logic<br>1: Negative logic<br>Decade: Y2 (same as unit's place)<br>Hundreds place: Relay 1 output (same as unit's place)<br>Thousands place: Relay 2 output (same as unit's place) | 0000 | × |
| F05.09 | Detection width of frequency attained | 0.00～20.00Hz | 5.00Hz | × |
| F05.10 | FDT1 upper bound | 0.00～Fmax | 30.00Hz | × |
| F05.11 | FDT1 lower bound | 0.00～Fmax | 30.00Hz | × |
| F05.12 | FDT2 upper bound | 0.00～Fmax | 30.00Hz | × |
| F05.13 | FDT2 lower bound | 0.00～Fmax | 30.00Hz | × |
| F05.14 | Consecutive running time | 0.0～6000.0Min 0.0:Disabled | 0.0Min | × |
| F05.15 | Accumulative power-on time setting | 0～65535h 0:Disabled | 0h | × |
| F05.16 | Accumulative running time setting | 0～65535h 0:Disabled | 0h | × |
| F05.17 | Brake control selection | 0: Disabled<br>1: Enabled | 0 | × |
| F05.18 | Brake opened frequency | Closed frequency ~30.00Hz | 2.50Hz | × |
| F05.19 | Brake opened current | 0.0~200.0% | 0.0% | △ |
| F05.20 | Brake open waiting time | 0.00~10.00s | 0.00s | × |
| F05.21 | Brake open operating time | 0.00~10.00s | 0.50s | × |
| F05.22 | Brake closed frequency | 0.00Hz~opened frequency | 2.00Hz | × |
| F05.23 | Brake close waiting time | 0.00~10.00s | 0.00s | × |
| F05.24 | Brake close operating time | 0.00~10.00s | 0.50s | × |
| **Group F06 Analog and Pulse Input** | | | | |
| F06.00 | Minimum input of curve AI1 | 0.0%～input of inflection point1 of curve AI1 | 1.0% | △ |
| F06.01 | Set value corresponding to minimum input of curve AI1 | -100.0～100.0% | 0.0% | △ |
| F06.02 | Input of inflection point 1 of curve AI1 | Minimum input of curve AI1～Input of inflection point 2 of curve AI1 | 100.0% | △ |
| F06.03 | Set value corresponding to input of inflection point 1 of curve AI1 | -100.0～100.0% | 100.0% | △ |
| F06.04 | Input of inflection point 2 of curve AI1 | Input of inflection point 1 of curve AI1～Maximum input of curve AI1 | 100.0% | △ |
| F06.05 | Set value corresponding to input of inflection point 2 of curve AI1 | -100.0～100.0% | 100.0% | △ |
| F06.06 | Maximum input of curve AI1 | Input of inflection point 2 of curve AI1～100.0% | 100.0% | △ |
| F06.07 | Set value corresponding to maximum input of curve AI1 | -100.0～100.0% | 100.0% | △ |
| F06.08 | Minimum input of curve AI2 | 0.0%～input of inflection point1 of curve AI2 | 1.0% | △ |

| | | | | |
|---|---|---|---|---|
| F06.09 | Set value corresponding to minimum input of curve AI2 | -100.0～100.0% | 0.0% | △ |
| F06.10 | Input of inflection point 1 of curve AI2 | Minimum input of curve AI1～Input of inflection point 2 of curve AI2 | 100.0% | △ |
| F06.11 | Set value corresponding to input of inflection point 1 of curve AI2 | -100.0～100.0% | 100.0% | △ |
| F06.12 | Input of inflection point 2 of curve AI2 | Input of inflection point 1 of curve AI2～Maximum input of curve AI2 | 100.0% | △ |
| F06.13 | Set value corresponding to input of inflection point 2 of curve AI2 | -100.0～100.0% | 100.0% | △ |
| F06.14 | Maximum input of curve AI2 | Input of inflection point A of curve AI2～100.0% | 100.0% | △ |
| F06.15 | Set value corresponding to maximum input of curve AI2 | -100.0～100.0% | 100.0% | △ |
| F06.16 | Minimum input of curve AI3 | 0.0%～input of inflection point1 of curve AI3 | 0.0% | △ |
| F06.17 | Set value corresponding to minimum input of curve AI3 | -100.0～100.0% | -100.0% | △ |
| F06.18 | Input of inflection point 1 of curve AI3 | Minimum input of curve AI1～Input of inflection point 2 of curve AI3 | 25.0% | △ |
| F06.19 | Set value corresponding to input of inflection point 1 of curve AI3 | -100.0～100.0% | -50.0% | △ |
| F06.20 | Input of inflection point 2 of curve AI3 | Input of inflection point 1 of curve AI3～Maximum input of curve AI3 | 75.0% | △ |
| F06.21 | Set value corresponding to input of inflection point 2 of curve AI3 | -100.0～100.0% | 25.0% | △ |
| F06.22 | Maximum input of curve AI3 | Input of inflection point A of curve AI3～100.0% | 100.0% | △ |
| F06.23 | Set value corresponding to maximum input of curve AI3 | -100.0～100.0% | 100.0% | △ |
| F06.24 | Minimum input of curve keypad potentiometer | 0.0～Maximum input of curve keypad potentiometer | 0.5% | △ |
| F06.25 | Set value corresponding to minimum input of curve keypad potentiometer | -100.0～100.0% | 0.0% | △ |
| F06.26 | Maximum input of curve keypad potentiometer | Minimum input of curve keypad potentiometer～100.0 | 99.9% | △ |
| F06.27 | Set value corresponding to maximum input of curve keypad potentiometer | -100.0～100.0% | 100.0% | △ |
| F06.28 | AI1 terminal filtering time | 0.000～10.000s | 0.100s | △ |
| F06.29 | AI2 terminal filtering time | 0.000～10.000s | 0.100s | △ |
| F06.30 | AI3 terminal filtering time | 0.000～10.000s | 0.100s | △ |
| F06.31 | Keypad potentiometer filtering time | 0.000～10.000s | 0.100s | △ |
| F06.32 | Minimum input of curve HI | 0.00 kHz～Maximum input of curve | 0.00kHz | △ |

| | | | | |
|---|---|---|---|---|
| | | HI | | |
| F06.33 | Set value corresponding to minimum input of curve HI | -100.0～100.0% | 0.0% | △ |
| F06.34 | Maximum input of curve HI | Minimum input of curve HI～100.00kHz | 50.00kHz | △ |
| F06.35 | Set value corresponding to maximum input of curve HI | -100.0～100.0% | 100.0% | △ |
| F06.36 | HI terminal filtering time | 0.000～10.000s | 0.100s | △ |
| **Group F07 Analog and Pulse Output** | | | | |
| F07.00 | AO1 output function | 00: No output<br>01: Output frequency<br>02: Command frequency<br>03: Output current<br>04: Output voltage<br>05: Output power<br>06: Bus voltage<br>07: +10V<br>08: keypad potentiometer<br>09: AI1<br>10: AI2<br>11: AI3<br>12: HI<br>13: Output torque<br>14: Ao communication given 1<br>15: Ao communication given 2 | 1 | × |
| F07.01 | AO2 output function | | 2 | × |
| F07.02 | Y2/HO output function (when used as HO) | | 3 | × |
| F07.03 | AO1 offset | -100.0～100.0% | 0.0% | △ |
| F07.04 | AO1 gain | -2.000～2.000 | 1.000 | △ |
| F07.05 | AO1 filtering time | 0.000～10.000s | 0.000s | △ |
| F07.06 | AO2 offset | -100.0～100.0% | 0.00% | △ |
| F07.07 | AO2 gain | -2.000～2.000 | 1.000 | △ |
| F07.08 | AO2 filtering time | 0.000～10.000s | 0.000s | △ |
| F07.09 | HO maximum output pulse frequency | 0.01～100.00kHz | 50.00kHz | △ |
| F07.10 | HO output filtering time | 0.000～10.000s | 0.010s | △ |
| **Group F08 Parameters of Motor 1** | | | | |
| F08.00 | Motor 1 type selection | 0: Three phase asynchronous motors<br>1: Synchronous motors<br>2: Single phase asynchronous motors（Remove capacity）<br>3: Single phase asynchronous motors（No need to remove capacity） | 0 | × |
| F08.01 | Power rating of motor 1 | 0.1～1000.0kW | Model defined | × |
| F08.02 | Rated voltage of motor 1 | 60～660V | Model defined | × |
| F08.03 | Rated current of motor 1 | 0.1～1500.0A | Model defined | × |
| F08.04 | Rated frequency of motor 1 | 20.00～Fmax | Model defined | × |
| F08.05 | Rated speed of motor 1 | 1～30000 | Model defined | × |
| F08.08 | Stator resistance R1 of | 0.001～65.535Ω | Model | × |

| | | | | |
|---|---|---|---|---|
| | async motor 1 | | defined | |
| F08.09 | Rotor resistance R2 of async motor 1 | 0.001～65.535Ω | Model defined | × |
| F08.10 | Leakage inductance L1 of async motor 1 | 0.01～655.35mH | Model defined | × |
| F08.11 | Mutual inductance L2 of asynchronous motor 1 | 0.1～6553.5mH | Model defined | × |
| F08.12 | No-load current of async motor 1 | 0.1～1500.0A | Model defined | × |
| F08.13 | Field weakening coeff 1 of async motor 1 | 0.0～100.0 | 87% | × |
| F08.14 | Field weakening coeff 2 of async motor 1 | 0.0～100.0 | 75% | × |
| F08.15 | Field weakening coeff 3 of async motor 1 | 0.0～100.0 | 70% | × |
| F08.16 | Stator resistance of sync motor | 0.001～65.535Ω | Model defined | × |
| F08.17 | Direct axis inductance of sync motor | 0.01～655.35mH | Model defined | × |
| F08.18 | Quadrature axis inductance of sync motor | 0.01～655.35mH | Model defined | × |
| F08.19 | Back EMF of sync motor | 0～65535V | Model defined | × |
| F08.20 | Installation angle of encoder | 0.0～359.9° | 0.0° | × |
| F08.21 | Motor's pole number | 0～1000 | 4 | ⊙ |
| F08.22 | Find encoder origin at begining | 0: Not find<br>1: Find | 1 | × |
| F08.30 | Autotuning of motor 1 | 0: No autotuning<br>1: Static autotuning of motor<br>2: Rotary autotuning of motor | 0 | × |
| **Group F09 V/f Control Parameters of Motor 1** | | | | |
| F09.00 | V/f curve setting | 00: Linear V/f<br>01: Multi-stage V/f<br>02:1.2nd power V/F<br>03:1.4th power V/F<br>04:1.6th power V/F<br>05:1.8th power V/F<br>06: 2.0nd power V/F<br>07: V/F complete separation<br>08: V/F half separation<br>09: 1.2 power inverse curve V/F<br>10: 1.4 power inverse curve V/F<br>11: 1.6 power inverse curve V/F<br>12: 1.8 power inverse curve V/F<br>13: 2.0 power inverse curve V/F | 0 | × |
| F09.01 | Torque boost | 0.1%–30.0% 0.0% (fixed torque boost) | 0.0% | △ |
| F09.02 | Cut-off frequency of torque boost | 0.00～Fmax | 50.00Hz | △ |
| F09.03 | Multi-point V/F frequency 1(F1) | 0.00～F09.05 | 0.00Hz | △ |
| F09.04 | Multi-point V/F voltage 1 (V1) | 0.0～100.0 | 5.0% | △ |
| F09.05 | Multi-point V/F frequency 2(F2) | F09.03～F09.05 | 5.00Hz | △ |

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|---|---|---|---|---|
| F09.06 | Multi-point V/F voltage 2 (V2) | 0.0～100.0 | 14.0% | △ |
| F09.07 | Multi-point V/F frequency 3(F3) | F09.05～F09.09 | 25.00Hz | △ |
| F09.08 | Multi-point V/F voltage 3 (V3) | 0.0～100.0 | 50.0% | △ |
| F09.09 | Multi-point V/F frequency 4(F4) | F09.07～rated motor frequency | 50.00Hz | △ |
| F09.10 | Multi-point V/F voltage 4 (V4) | 0.0～100.0 Ue=100.0% | 100.0% | △ |
| F09.11 | V/F slip compensation gain | 0.0～300.0% | 80.0% | △ |
| F09.12 | Stator voltagedrop compensation gain | 0.0～200.0% | 100.0% | △ |
| F09.13 | Excitation boost gain | 0.0～200.0% | 100.0% | △ |
| F09.14 | Oscillation Suppression | 0.0～300.0% | 100.0% | △ |
| F09.15 | Voltage source for V/F separation | 0: Digital setting (F09.16)<br>1: keypad potentiometer<br>2: AI1<br>3: Multi-reference<br>4: Pulse setting ( DI7/HI )<br>5: PID<br>6: AI2<br>7: AI3 | 0 | × |
| F09.16 | Voltage digital setting for V/F separation | 0 V to rated motor voltage | 0.0% | △ |
| F09.17 | Voltage rise time of V/F separation | 0.0～6000.0s<br>It indicates the time for the voltage rising from 0 V to rated Motor voltage. | 0.1s | △ |
| F09.18 | IQ filtering time below VVF 0.5Hz | F09.19～3000ms | 500ms | × |
| F09.19 | IQ filtering time above VVF 2Hz | 1ms～F09.18 | 100ms | × |
| F09.20 | Forward torque correction | 0.0～5.0% | 0.0% | △ |
| F09.21 | Reverse torque correction | 0.0～5.0% | 1.0% | △ |
| F09.22 | PMSM acceleration current compensation setting | 0.0～200.0% | 0.0% | △ |
| F09.23 | PMSM compensation time decreased after acceleration | 0.0～100.0s | 2.0s | △ |
| F09.24 | PMSM ID current value will be maintained after accelerating. | 0.0～200.0% | 0.0% | △ |
| **Group F10 Vector Control Parameters of Motor 1** | | | | |
| F10.00 | Speed/torque control | 0: speed control<br>1: torque control | 0 | × |
| F10.01 | ASR low-speed proportional gain Kp1 | 0.0～100.0 | 15.0 | △ |
| F10.02 | ASR low-speed integration time Ti1 | 0.001～30.000s | 0.050s | △ |
| F10.03 | ASR switching frequency 1 | 0.00～F10.06 | 5.00Hz | △ |
| F10.04 | ASR high-speed proportional gain Kp2 | 1～100.0 | 10.0 | △ |

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|---|---|---|---|---|
| F10.05 | ASR high-speed integration time Ti2 | 0.001～30.000s | 0.100s | △ |
| F10.06 | ASR switching frequency 2 | F10.03～Fmax | 10.00Hz | △ |
| F10.07 | ASR input filtering time | 0.0～500.0ms | 3.0ms | △ |
| F10.08 | ASR output filtering time | 0.0～500.0ms | 0.0ms | △ |
| F10.09 | Vector control slip gain | 50～200% | 100% | △ |
| F10.10 | Digital setting of torque upper limit in speed control mode | 80.0～200.0% | 165.0% | × |
| F10.11 | Excitation adjustment proportional gain Kp1 | 0.00～10.00 | 0.50 | △ |
| F10.12 | Excitation adjustment integral gain Ti1 | 0.0～3000.0ms | 10.0ms | △ |
| F10.13 | Torque adjustment proportional gain Kp2 | 0.00～10.00 | 0.50 | △ |
| F10.14 | Torque adjustment integral gain Ti2 | 0.0～3000.0ms | 10.0ms | △ |
| F10.15 | Excitation gain coefficient | 50.0~200% | 100% | △ |
| F10.16 | Torque setting source under torque control | 0：Set by F10.17<br>1：Keypad potentiometer<br>2：AI1<br>3：AI2<br>4：AI3<br>5：Pulse setting ( DI7/HI )<br>6：Communication setting | 0 | × |
| F10.17 | Digital setting of torque | -200.0～200.0% | 50.0% | △ |
| F10.18 | Forward speed limited value under torque control | 0.00～Fmax | 50.00Hz | △ |
| F10.19 | Reverse speed limited value under torque contro | 0.00～ Fmax | 50.00Hz | △ |
| F10.20 | Set torque accel time | 0.0～6000.0s | 0.0s | △ |
| F10.21 | Set torque decel time | 0.0～6000.0s | 0.0s | △ |
| F10.22 | Static friction torque compensation | 0.0～100.0% | 5.00% | △ |
| F10.23 | Static friction frequency range | 0.00～20.00Hz | 1.00Hz | △ |
| F10.24 | Sliding friction torque compensation | 0.0～100.0% | 1.0% | △ |
| F10.25 | SVC optimization method | 0: Optimization method 1<br>1: Optimization method 2<br>2: Optimization method 3 | 1 | × |
| F10.26 | Max Frequency source under torque control | 0：Set by F10.18 & F10.19<br>1：Keypad potentiometer<br>2：AI1<br>3：AI2<br>4：AI3<br>5：Pulse setting ( DI7/HI ) | 0 | × |
| F10.27 | PMSM Start excitation current | 0.0～150.0% | 50% | × |
| F10.28 | PMSM flux-weakening control | 0: Invalid<br>1: Valid | 1 | × |
| F10.29 | PMSM flux-weakening voltage | 70.0～100.0% | 95% | △ |

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|---|---|---|---|---|
| F10.30 | PMSM r flux-weakening gain Kp | 0.0～500.0% | 50.0% | △ |
| F10.31 | PMSM flux-weakening integral Ti | 0.00～60.00s | 0.50s | △ |
| F10.32 | PMSM flux-weakening limit | 0.0～200.0% | 100.0% | △ |
| F10.33 | PMSM excitation current frequency high point | F10.34～600.00Hz | 15.00Hz | △ |
| F10.34 | PMSM excitation current frequency low point | 0.0～F10.33 | 10.00Hz | △ |
| F10.35 | PMSM excitation current conversion delay | 0.0～10.0s | 1.0s | △ |
| F10.36 | PMSM speed estimation Kp | 0.00～10.00 | 2.00 | △ |
| F10.37 | PMSM speed estimation Ti | 0.1～1000.0ms | 20.0ms | △ |
| **Group F11 Protection Parameters** | | | | |
| F11.00 | Current limit control | 0: Current limit disabled<br>1: Current limit mode 1<br>2: Current limit mode 2 | 2 | × |
| F11.01 | Current limit | 100.0～200.0% | 150.0% | × |
| F11.02 | Frequency decreasing time(limit current in constant speed operation) | 0.0～6000.0s | 5.0s | △ |
| F11.03 | Current limit mode 2 proportion gain | 0.1～100.0% | 3.0% | △ |
| F11.04 | Current limit mode 2 integral time | 0.00～10.00s | 10.00s | △ |
| F11.05 | Overvoltage Stall Control | 0: Overvoltage stall disabled<br>1: Overvoltage stall mode 1<br>2: Overvoltage stall mode 2 | 1 | × |
| F11.06 | Overvoltage stall voltage | 600～800V | 730V | × |
| F11.07 | Overvoltage Stall Mode 2 Proportion Gain | 0.0～100.0% | 50.0% | △ |
| F11.08 | Overvoltage stall mode 2 frequency limit | 0.00～50.00Hz | 5.00Hz | × |
| F11.10 | Protection action 1 | Unit's place: Bus undervoltage<br>0: Fault reported and coast to stop<br>1: Stop according to the stop mode<br>2: Fault reported but continue to run<br>3: Fault protection disabled<br>Ten's digit :Power input phase Loss (Err09)(Same as unit's place )<br>Hundred's digit :Power output phase loss(Err10)(Same as unit's place )<br>Thousand's digit:Motor overload (Err11)(Same as unit's place )<br>Ten thousand's digit:Inverter overload(Err11)(Same as unit's place ) | 03330 | × |
| F11.11 | Protection action 2 | External equipment fault（Err13)<br>0: Fault reported and coast to stop<br>1: Stop according to the stop mode | 00000 | × |

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|---|---|---|---|---|
| | | 2: Fault reported but continue to run<br>Ten's digit: EEPROM read/write fault (Err15) (Same as unit's place)<br>Hundred's digit: Communication overtime error (Err18) (Same as unit's place)<br>Thousand's digit: PID feedback loss (Err19) (Same as unit's place)<br>Ten thousand's digit: Continuous running time reached (Err20) (Same as unit's place) | | |
| F11.12 | Protection action 3 | Unit's place: Module temperature detection disconnection（Err24)<br>0: Fault reported and coast to stop<br>1: Stop according to the stop mode<br>2: Fault reported but continue to run<br>Ten's digit: Load becoming 0 (Err25) (Same as unit's place) | 00030 | × |
| F11.14 | Frequency selection for continuing to run upon fault | 0: Current running frequency<br>1: Set frequency<br>2: Frequency upper limit<br>3: Frequency lower limit<br>4: Backup frequency upon abnormality | 1 | × |
| F11.15 | Backup frequency upon abnormality | 0.00～Fmax | 0.00Hz | × |
| F11.17 | Motor overload protection time | 30.0～300.0s | 60.0s | × |
| F11.18 | Overload alarm | Unit's place: detection option:<br>0: Always detect<br>1: Detect at constant speed only<br>Ten's digit : compared object<br>0: Rated current of motor<br>1: Rated current of drive<br>Hundred's digit: Fault reported<br>0:No fault reported<br>1:Fault reported<br>Thousand's digit: whether to decelerate or not when overload alarm<br>0: No deceleration<br>1: Deceleration<br>Ten thousand's place: Set overload level mode<br>0:F11.19 set<br>1:F11.19 * VP<br>2:F11.19 * AI1<br>3:F11.19 * AI2<br>4:F11.19 * AI3 | 00010 | × |
| F11.19 | Overload alarm threshold | 20.0～200.0% | 130.0% | × |
| F11.20 | Overload alarm activated time that exceeding threshold | 0.1～60.0s | 5.0s | × |
| F11.21 | Inverter overheat warning threshold | 50～overheat Temperature | Model defined | × |

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|---|---|---|---|---|
| F11.22 | Detection level of load loss | 5.0～100.0% | 20.0% | × |
| F11.23 | Detection time of load loss | 0.1～60.0s | 5.0s | × |
| F11.24 | Action selection at instantaneous power failure | 0: Disabled<br>1: Deceleration<br>2: Bus voltage constant control | 0 | × |
| F11.25 | Decel time at instantaneous power failure | 0.0～6000.0s | 5.0s | △ |
| F11.26 | Rapid current limit | 0: Disabled<br>1: Enabled | 0 | × |
| F11.27 | Times of automatic trip(fault) reset | 0～20 | 0 | × |
| F11.28 | Interval of automatic trip(fault) reset | 0.1～100.0s | 1.0s | × |
| F11.29 | DO action during fault auto reset | 0: Not act<br>1: Act | 0 | × |
| F11.30 | Instantaneous power off bus voltage | 60.0%～Recovery voltage | 80.0% | △ |
| F11.31 | Instantaneous power off recovery voltage | Power off voltage～100.0% | 85.0% | △ |
| F11.32 | Instantaneous power off voltage detection time | 0.01～10.00s | 0.10s | △ |
| F11.33 | Instantaneous power off Kp | 0.1～100.0% | 40.0% | △ |
| F11.34 | Instantaneous power off integration time Ti | 0.00～10.00s （0.00：Integration invalid） | 0.10s | △ |
| F11.35 | Motor temperature sensor type | 0:None<br>1:PT100<br>2:PT1000<br>3:KTY84 | 0 | × |
| F11.36 | Zero drift value of motor temperature sensor | -100～100℃ | 0 | △ |
| F11.37 | Reserved | | | |
| F11.38 | Motor temperature warning action threshold | 0～200℃ | 90℃ | △ |
| F11.39 | Motor temperature protection action threshold | 0～200℃ | 110℃ | △ |
| **Group F12: Multi-Reference and Simple PLC Function** | | | | |
| F12.00 | Reference 0 | -100.0～100.0% | 0.0% | △ |
| F12.01 | Reference 1 | -100.0～100.0% | 0.0% | △ |
| F12.02 | Reference 2 | -100.0～100.0% | 0.0% | △ |
| F12.03 | Reference 3 | -100.0～100.0% | 0.0% | △ |
| F12.04 | Reference 4 | -100.0～100.0% | 0.0% | △ |
| F12.05 | Reference 5 | -100.0～100.0% | 0.0% | △ |
| F12.06 | Reference 6 | -100.0～100.0% | 0.0% | △ |
| F12.07 | Reference 7 | -100.0～100.0% | 0.0% | △ |
| F12.08 | Reference 8 | -100.0～100.0% | 0.0% | △ |
| F12.09 | Reference 9 | -100.0～100.0% | 0.0% | △ |
| F12.10 | Reference 10 | -100.0～100.0% | 0.0% | △ |
| F12.11 | Reference 11 | -100.0～100.0% | 0.0% | △ |
| F12.12 | Reference 12 | -100.0～100.0% | 0.0% | △ |
| F12.13 | Reference 13 | -100.0～100.0% | 0.0% | △ |
| F12.14 | Reference 14 | -100.0～100.0% | 0.0% | △ |
| F12.15 | Reference 15 | -100.0～100.0% | 0.0% | △ |

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|---|---|---|---|---|
| F12.16 | Reference 0 source | 0: Digital setting（F12.00）<br>1: keypad potentiometer<br>2: AI1<br>3: Process PID output<br>4: X7/HI pulse input<br>5: AI2<br>6: AI3 | 0 | × |
| F12.17 | Running mode of simple PLC | Unit's place: PLC running mode<br>0: Stop after a single cycle<br>1: Continue to run with the last frequency after a single cycle<br>2: Repeat cycles<br>Decade: started mode<br>0: Continue to run from the step of stop (or fault)<br>1: Run from the first step “multi-step frequency 0”<br>2: Run from the eighth step “multi-step frequency 8”<br>3: Run from the fifteenth step “multi-step frequency 15”<br>Hundreds place:power loss memory<br>0: Memory disabled on power loss<br>1: Memory enabled on power loss<br>Thousands place: unit of simple PLC running time<br>0: Second (s)<br>1: Minute (min) | 0000 | × |
| F12.18 | Running time of step 0 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.19 | Running time of step 1 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.20 | Running time of step 2 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.21 | Running time of step 3 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.22 | Running time of step 4 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.23 | Running time of step 5 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.24 | Running time of step 6 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.25 | Running time of step 7 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.26 | Running time of step 8 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.27 | Running time of step 9 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.28 | Running time of step 10 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.29 | Running time of step 11 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.30 | Running time of step 12 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.31 | Running time of step 13 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.32 | Running time of step 14 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.33 | Running time of step 15 | 0.0～6000.0s(h) | 0.0s(h) | △ |
| F12.34 | Acceleration/deceleration time of simple PLC reference 0 | 0～3 | 0 | △ |
| F12.35 | Acceleration/deceleration time of simple PLC reference 1 | 0～3 | 0 | △ |
| F12.36 | Acceleration/deceleration time of simple PLC reference 2 | 0～3 | 0 | △ |

| | | | | |
|---|---|---|---|---|
| F12.37 | Acceleration/deceleration time of simple PLC reference 3 | 0～3 | 0 | △ |
| F12.38 | Acceleration/deceleration time of simple PLC reference 4 | 0～3 | 0 | △ |
| F12.39 | Acceleration/deceleration time of simple PLC reference 5 | 0～3 | 0 | △ |
| F12.40 | Acceleration/deceleration time of simple PLC reference 6 | 0～3 | 0 | △ |
| F12.41 | Acceleration/deceleration time of simple PLC reference 7 | 0～3 | 0 | △ |
| F12.42 | Acceleration/deceleration time of simple PLC reference 8 | 0～3 | 0 | △ |
| F12.43 | Acceleration/deceleration time of simple PLC reference 9 | 0～3 | 0 | △ |
| F12.44 | Acceleration/deceleration time of simple PLC reference 10 | 0～3 | 0 | △ |
| F12.45 | Acceleration/deceleration timeof simple PLC reference 11 | 0～3 | 0 | △ |
| F12.46 | Acceleration/deceleration time of simple PLC reference 12 | 0～3 | 0 | △ |
| F12.47 | Acceleration/deceleration time of simple PLC reference 13 | 0～3 | 0 | △ |
| F12.48 | Acceleration/deceleration time of simple PLC reference 14 | 0～3 | 0 | △ |
| F12.49 | Acceleration/deceleration time of simple PLC reference 15 | 0～3 | 0 | △ |
| F12.50 | UP/DOWN function selection of Multi-reference | Unit's digit: Action selection when power off<br>0:Zero clearing when power off<br>1:Hold when power off<br>Ten's digit: select if it can be reduced to negative<br>0:Disable<br>1:Enable | 00 | × |
| F12.51 | UP/DOWN speed of Multi-reference | 0.0～100.0% (0.0%Invalid) | 0.0% | △ |
| **Group F13 Process PID** | | | | |
| F13.00 | PID setting | 0: F13.01 digital setting<br>1:keypad potentiometer<br>2: AI1<br>3: Communication<br>4: Multi-Reference<br>5: DI7/HI pulse input<br>6: AI2 | 0 | × |

| | | | | |
|---|---|---|---|---|
| | | 7: AI3 | | |
| F13.01 | PID digital setting | 0.0～100.0% | 50.0% | △ |
| F13.02 | PID feedback | 0: AI1<br>1: AI2<br>2: Communication<br>3: AI1+AI2<br>4: AI1-AI2<br>5: Max{AI1，AI2}<br>6: Min{AI1，AI2}<br>7: DI7/HI pulse input<br>8: AI3 | 0 | × |
| F13.03 | PID setting feedback range | 0.0～6000.0 | 100.0 | △ |
| F13.04 | PID action direction | 0: Forward action<br>1: Reverse action | 0 | × |
| F13.05 | Filtering time of PID setting | 0.000～10.000s | 0.000s | △ |
| F13.06 | Filtering time of PID feedback | 0.000～10.000s | 0.000s | △ |
| F13.07 | Filtering time of PID output | 0.000～10.000s | 0.000s | △ |
| F13.08 | Proportional gain Kp1 | 0.0～100.0 | 1.0 | △ |
| F13.09 | Integration time Ti1 | 0.01～10.00s | 0.10s | △ |
| F13.10 | Differential time Td1 | 0.000～10.000s | 0.000s | △ |
| F13.11 | Proportional gain Kp2 | 0.0～100.0 | 1.0 | △ |
| F13.12 | Integration time Ti2 | 0.01～10.00s | 0.10s | △ |
| F13.13 | Differential time Td2 | 0.000～10.000s | 0.000s | △ |
| F13.14 | PID parameter switch | 0: No switch, determined by parameters Kp1, Ti1 and Td1<br>1: Auto switch on the basis of input offset<br>2: Switched by terminal | 0 | × |
| F13.15 | PID parameter switchover deviation 1 | 0.0～100.0% | 20.0% | × |
| F13.16 | PID parameter switchover deviation 2 | 0.0～100.0% | 80.0% | × |
| F13.17 | PID offset limit | 0.0～100.0% | 0.0% | × |
| F13.18 | PID integral property | Unit's digit (Whether to stop integral operation when the output reaches the limit)<br>0: Continue integral operation<br>1: Stop integral operation<br>Ten's digit (Integral separated)<br>0: Invalid<br>1: Valid | 00 | × |
| F13.19 | PID differential limit | 0.0～100.0% | 0.5% | × |
| F13.20 | PID initial value | 0.0～100.0% | 0.0% | × |
| F13.21 | Holding time of PID initial value | 0.0～6000.0s | 0.0s | × |
| F13.22 | PID output frequency upper limit | PID output frequency lower limit～100.0%（100.0% corresponds to maximum frequency ） | 100.0% | × |
| F13.23 | PID output frequency lower limit | –100.0%～PID output frequency lower limit | 0.0% | × |

| | | | | |
|---|---|---|---|---|
| F13.24 | Down limit of PID feedback loss | 0.1～100.0%<br>0.0%: Not judging feedback loss | 0.0% | × |
| F13.25 | Detection time for down limit of PID feedback loss | 0.0～30.0s | 1.0s | × |
| F13.26 | PID operation selection | Unit's digit: PID operation selection when stop<br>0:Do not operate when stop<br>1:Operate when stop<br>Ten's digit: output is limited by output frequency<br>0:No limited<br>1:limited<br>Hundred's digit: UP/DOWN digital given of PID<br>0:Zero clearing when power off<br>1:Hold when power off<br>Thousand's place: PID feedback loss detection mode<br>0:No detection when stop<br>1:Do detection when stop<br>Ten thousand's place: Action when PID feedback loss<br>0:Report fault<br>1:Ramp to stop | 00000 | × |
| F13.27 | UP/DWON speed of PID digital given | 0.0～100.0% (0.0% Invalid) | 0.0% | △ |
| F13.28 | Up limit of PID feedback loss | 0.1～100.0%<br>0.0%: Not judging feedback loss | 100.0% | × |
| F13.29 | Detection time for up limit of PID feedback loss | 0.0～30.0s | 1.0s | × |
| F13.30 | PID upper limit source selection | 0:F13.22<br>1:F13.22* keyboard potentiometer<br>2:F13.22*AI1<br>3:F13.22*AI2<br>4:F13.22 * HI (pulse input)<br>5:F13.22*AI3 | 0 | × |
| F13.31 | PID lower limit source selection | 0:F13.23<br>1:F13.23* keyboard potentiometer<br>2:F13.23*AI1<br>3:F13.23*AI2<br>4:F13.23 * HI (pulse input)<br>5:F13.23*AI3 | 0 | × |
| **Group F14: Swing Frequency, Fixed Length , Wakeup and Count** | | | | |
| F14.00 | Swing frequency setting mode | 0: Relative to the setting frequency<br>1: Relative to the maximum frequency | 0 | × |
| F14.01 | Swing frequency amplitude | 0.0～100.0% | 0.0% | △ |
| F14.02 | Jump frequency amplitude | 0.0～50.0% | 0.0% | △ |
| F14.03 | Rising Time of Swing frequency | 0.0～6000.0s | 5.0s | △ |
| F14.04 | Dropping Time of Swing frequency | 0.0～6000.0s | 5.0s | △ |
| F14.05 | Set length | 0m～65535m | 1000m | × |

| | | | | |
|---|---|---|---|---|
| F14.06 | Number of pulses per meter | 0.1～6553.5 | 100.0 | × |
| F14.07 | Command when the length attained | Unit's place: stop when the length reaches<br>0: Not stop<br>1: Stop<br>Ten's place: length calculation method<br>0: pulse by pulse<br>1: Reference maximum frequency<br>2: Refer to Ai1 channel<br>3: Refer to AI2 channel<br>4: Refer to AI3 channel | 00 | × |
| F14.08 | Set count value | 1～65535 | 1000 | × |
| F14.09 | Designated count value | 1～65535 | 1000 | × |
| F14.10 | Wakeup frequency | Dormant frequency (F14.12)～Fmax | 0.00Hz | △ |
| F14.11 | Wakeup delay time | 0.0～6000.0s | 0.0s | △ |
| F14.12 | Dormant frequency | 0.00～Wakeup frequency | 0.00Hz | △ |
| F14.13 | Dormant delay time | 0.0～6000.0s | 0.0s | △ |
| F14.14 | Wake up mode selection | 0: Frequency<br>1: Pressure | 0 | × |
| F14.15 | Dormancy mode selection | 0: Frequency<br>1: Pressure | 0 | × |
| F14.16 | Voltage feedback source | Unit's place: pressure feedback channel<br>0: AI1<br>1: AI2<br>2: DI7/HI pulse input<br>3: AI3<br>Ten's place: Dormancy mode<br>0:Dormancy on high pressure and wake up on low pressure<br>1:Dormancy on low pressure and wake up on high pressure | 00 | × |
| F14.17 | Wake up pressure | 0.0%～Dormancy pressure | 10.0% | △ |
| F14.18 | Dormancy pressure | Wake up pressure～100.0% | 50.0% | △ |
| **Group F15: Communication Parameters** | | | | |
| F15.00 | Baud rate | 0: 4800bps<br>1: 9600bps<br>2: 19200bps<br>3: 38400bps<br>4: 57600bps<br>5: 115200bps | 1 | × |
| F15.01 | Data format | No check, data format (1-8-N-2) for RTU<br>1: Even parity check, data format (1-8-E-1) for RTU<br>2: Odd Parity check, data format (1-8-O-1) for RTU<br>3: No check, data format(1-8-N-1) for RTU | 0 | × |
| F15.02 | Local address | 1～247　0: Broadcast address | 1 | × |
| F15.03 | Communication timeout | 0.0～60.0s | 0.0s | × |
| F15.04 | Response time delay | 0～200ms | 1ms | × |
| F15.05 | Master-slave | 0:The inverter is the slave | 0 | × |

| | | | | |
|---|---|---|---|---|
| | Communication Mode | 1:The inverter is the master | | |
| F15.06 | The Master Communication Sending Data | 0: Set frequency<br>1: Current running frequency | 0 | × |
| F15.07 | Message return when communication error | 0: No return<br>1: Return | 1 | |
| F15.08 | U group return value | 0: Positive and negative<br>1: Absolute value | 0 | △ |
| **Group F16 Keys and Display of Keypad Parameters** | | | | |
| F16.00 | MF.K key setting | 0: No function<br>1: Jog<br>2: Forward/reverse switchover<br>3: Run command sources shifted<br>4: Jog reverse | 1 | × |
| F16.01 | Keyboard operation display | Unit's digit: Function selection of STOP/RESET key<br>0: stop function of STOP/RESET key is valid only in keyboard operation mode<br>1: Stop function of STOP/RES key is valid in any operation mode<br>Ten's digit: Speed display（U00.05）<br>0: According to the actual speed<br>1: Multiply frequency by speed coefficient(F16.11)<br>Hundred's digit: Decimal places<br>0: No decimal places<br>1: One decimal places<br>2: Two decimal places<br>3: Three decimal places | 001 | × |
| F16.02 | Keys locked option | 0: Not locked<br>1: Full locked<br>2: Keys locked other than RUN, STOP/RST<br>3: Keys locked other than STOP/RST<br>4: Keys locked other than >> | 0 | × |
| F16.03 | LED displayed parameters setting 1 on running status | 0～99(correspond U00.00～U00.99) | 0 | △ |
| F16.04 | LED displayed parameters setting 2 on running status | 0～99(correspond U00.00～U00.99) | 6 | △ |
| F16.05 | LED displayed parameters setting 3 on running status | 0～99(correspond U00.00～U00.99) | 3 | △ |
| F16.06 | LED displayed parameters setting 4 on running status | 0～99(correspond U00.00～U00.99) | 2 | △ |
| F16.07 | LED displayed parameters setting 1 on stop status | 0～99(correspond U00.00～U00.99) | 1 | △ |
| F16.08 | LED displayed parameters setting 2 on stop status | 0～99(correspond U00.00～U00.99) | 6 | △ |
| F16.09 | LED displayed parameters setting 3 on stop status | 0～99(correspond U00.00～U00.99) | 15 | △ |
| F16.10 | LED displayed parameters setting 4 on stop status | 0～99(correspond U00.00～U00.99) | 16 | △ |
| F16.11 | Speed display coefficient | 0.00~100.00 | 1.00 | △ |
| F16.12 | Power display coefficient | 0.0~300.0% | 100.0% | △ |
| F16.13 | Display error between | 0.00Hz～5.00Hz | 0.10Hz | △ |

| | | | | |
|---|---|---|---|---|
| | U00.00 and U00.01 | | | |
| **Group F17 User-defined Display Parameters** | | | | |
| F17.00 | User-defined Display Parameter 0 | 00.00～49.99 | 00.03 | △ |
| F17.01 | User-defined Display Parameter 1 | 00.00～49.99 | 01.01 | △ |
| F17.02 | User-defined Display Parameter 2 | 00.00～49.99 | 01.02 | △ |
| F17.03 | User-defined Display Parameter 3 | 00.00～49.99 | 01.08 | △ |
| F17.04 | User-defined Display Parameter 4 | 00.00～49.99 | 01.09 | △ |
| F17.05 | User-defined Display Parameter 5 | 00.00～49.99 | 02.00 | △ |
| F17.06 | User-defined Display Parameter 6 | 00.00～49.99 | 02.01 | △ |
| F17.07 | User-defined Display Parameter 7 | 00.00～49.99 | 02.12 | △ |
| F17.08 | User-defined Display Parameter 8 | 00.00～49.99 | 03.00 | △ |
| F17.09 | User-defined Display Parameter 9 | 00.00～49.99 | 03.01 | △ |
| F17.10 | User-defined Display Parameter 10 | 00.00～49.99 | 04.00 | △ |
| F17.11 | User-defined Display Parameter 11 | 00.00～49.99 | 04.01 | △ |
| F17.12 | User-defined Display Parameter 12 | 00.00～49.99 | 04.02 | △ |
| F17.13 | User-defined Display Parameter 13 | 00.00～49.99 | 04.03 | △ |
| F17.14 | User-defined Display Parameter 14 | 00.00～49.99 | 05.02 | △ |
| F17.15 | User-defined Display Parameter 15 | 00.00～49.99 | 08.01 | △ |
| F17.16 | User-defined Display Parameter 16 | 00.00～49.99 | 08.02 | △ |
| F17.17 | User-defined Display Parameter 17 | 00.00～49.99 | 08.03 | △ |
| F17.18 | User-defined Display Parameter 18 | 00.00～49.99 | 08.04 | △ |
| F17.19 | User-defined Display Parameter 19 | 00.00～49.99 | 08.05 | △ |
| F17.20 | User-defined Display Parameter 20 | 00.00～49.99 | 08.30 | △ |
| F17.21 | User-defined Display Parameter 21 | 00.00～49.99 | 11.10 | △ |
| F17.22 | User-defined Display Parameter 22 | 00.00～49.99 | 13.00 | △ |
| F17.23 | User-defined Display Parameter 23 | 00.00～49.99 | 13.01 | △ |
| F17.24 | User-defined Display Parameter 24 | 00.00～49.99 | 13.02 | △ |
| F17.25 | User-defined Display Parameter 25 | 00.00～49.99 | 13.08 | △ |
| F17.26 | User-defined Display Parameter 26 | 00.00～49.99 | 13.09 | △ |
| F17.27 | User-defined Display | 00.00～49.99 | 00.00 | △ |

| | | | | |
|---|---|---|---|---|
| | Parameter 27 | | | |
| F17.28 | User-defined Display Parameter 28 | 00.00～49.99 | 00.00 | △ |
| F17.29 | User-defined Display Parameter 29 | 00.00～49.99 | 00.00 | △ |
| **F22Group:Virtual IO** | | | | |
| F22.00 | Function selection of virtual VDI1 terminal | The same as function code F04.00 | 0 | × |
| F22.01 | Function selection of virtual VDI2 terminal | The same as function code F04.00 | 0 | × |
| F22.02 | Function selection of virtual VDI3 terminal | The same as function code F04.00 | 0 | × |
| F22.03 | Function selection of virtual VDI4 terminal | The same as function code F04.00 | 0 | × |
| F22.04 | Function selection of virtual VDI5 terminal | The same as function code F04.00 | 0 | × |
| F22.05 | Valid status setting mode of virtual VDI terminals | （VDI5、VDI4、VDI3、VDI2、VDI1）<br>0:Validity of VDI depends on virual VDOx's status<br>1:Validity of VDI set by function code F22.06 | 00000 | × |
| F22.06 | Settings of virtual VDI terminal status | （VDI5、VDI4、VDI3、VDI2、VDI1）<br>0: Invalid<br>1: Valid | 00000 | △ |
| F22.07 | Function selection of virtual VDO1 terminals output | 0 : Internal short circuited to physics DIx<br>Other: The same as function code F05.00 | 0 | △ |
| F22.08 | Function selection of virtual VDO2 terminals output | 0 : Internal short circuited to physics DIx<br>Other: The same as function code F05.00 | 0 | △ |
| F22.09 | Function selection of virtual VDO3 terminals output | 0 : Internal short circuited to physics DIx<br>Other: The same as function code F05.00 | 0 | △ |
| F22.10 | Function selection of virtual VDO4 terminals output | 0 : Internal short circuited to physics DIx<br>Other: The same as function code F05.00 | 0 | △ |
| F22.11 | Function selection of virtual VDO5 terminals output | 0 : Internal short circuited to physics DIx<br>Other: The same as function code F05.00 | 0 | △ |
| F22.12 | Virtual VDO1 output delay time | 0.0s~6000.0s | 0.0s | △ |
| F22.13 | Virtual VDO2 output delay time | 0.0s~6000.0s | 0.0s | △ |
| F22.14 | Virtual VDO3 output delay time | 0.0s~6000.0s | 0.0s | △ |
| F22.15 | Virtual VDO4 output delay time | 0.0s~6000.0s | 0.0s | △ |
| F22.16 | Virtual VDO5 output delay time | 0.0s~6000.0s | 0.0s | △ |
| F22.17 | VDO output terminal positive and negative logic | VDO5、VDO4、VDO3、VDO2、VDO1<br>0: Positive logic<br>1: Negtive logic | 00000 | △ |

| | | | | |
|---|---|---|---|---|
| **U00 Group: Status Monitoring** | | | | |
| U00.00 | Output Frequency | 0.00～Fup | 0.00Hz | ⊙ |
| U00.01 | Setting Frequency | 0.00～Fmax | 0.00Hz | ⊙ |
| U00.02 | Actual value of output voltage | 0～660V | 0.0V | ⊙ |
| U00.03 | Actual value of output current | 0.0～3000.0A | 0.0A | ⊙ |
| U00.04 | Output Power | -3000.0～3000.0kW | 0.0kW | ⊙ |
| U00.05 | Output Rotation-rate | 0～60000rpm | 0rpm | ⊙ |
| U00.06 | DC Bus Voltage | 0～1200V | 0V | ⊙ |
| U00.07 | Synchronization Frequency | 0.00～Fup | 0.00Hz | ⊙ |
| U00.08 | PLC Stage | 1～15 | 1 | ⊙ |
| U00.09 | Program Running Time | 0.0～6000.0s(h) | 0.0s(h) | ⊙ |
| U00.10 | PID Given | 0～60000 | 0 | ⊙ |
| U00.11 | PID Arithmetic Feedback | 0～60000 | 0 | ⊙ |
| U00.12 | DI1～DI5 Input Status | DI5 DI4 DI3 DI2 DI1 | 00000 | ⊙ |
| U00.13 | DI6～DI7 Input Status | DI7 DI6 | 00 | ⊙ |
| U00.14 | Digital Output Status | R2R1 Y2 Y1 | 0000 | ⊙ |
| U00.15 | AI1 Input | 0.0～100.0% | 0.0% | ⊙ |
| U00.16 | AI2 Input | 0.0～100.0% | 0.0% | ⊙ |
| U00.17 | AI3 Input | -100.0～100.0% | 0.0% | ⊙ |
| U00.18 | Keyboard Potentiometer Input | 0.0～100.0% | 0.0% | ⊙ |
| U00.19 | HI Pulse Input Frequency | 0.00～100.00kHz | 0.00kHz | ⊙ |
| U00.20 | A01 Output | 0.0～100.0% | 0.0% | ⊙ |
| U00.21 | A02 Output | 0.0～100.0% | 0.0% | ⊙ |
| U00.22 | HO Pulse Output Frequency | 0.00～100.00kHz | 0.00kHz | ⊙ |
| U00.23 | Temperature of Inverter Module | -40.0℃～120.0℃ | 0.0℃ | ⊙ |
| U00.24 | The Power-on Time | 0～65535min | 0min | ⊙ |
| U00.25 | The Running Time | 0～6553.5min | 0.0min | ⊙ |
| U00.26 | Cumulative Power-on Time | 0～65535h | 0h | ⊙ |
| U00.27 | Cumulative Running Time | 0～65535h | 0h | ⊙ |
| U00.28 | Actual Count Value | 0～65535 | 0 | ⊙ |
| U00.29 | Actual Length Value | 0～65535m | 0m | ⊙ |
| U00.30 | Line Speed | 0～65535m/min | 0m/Min | ⊙ |
| U00.31 | Output Torque | 0.0～300.0% | 0.0% | ⊙ |
| U00.35 | Power consumption | 0～65535KWh | 0 | ⊙ |
| **U01 Group: Failure Record** | | | | |
| U01.00 | Current Fault Category | Err00~Err32 | Err00 | ⊙ |
| U01.01 | Output frequency of the current fault | 0.00～Fup | 0.00Hz | ⊙ |
| U01.02 | Output current of the current fault | 0.0～3000.0A | 0.0A | ⊙ |
| U01.03 | c of the current fault | 0～1200V | 0V | ⊙ |
| U01.04 | Cumulative runtime of the current fault | 0～65535h | 0h | ⊙ |
| U01.05 | Former one fault category | Like the latest one fault record | Err00 | ⊙ |
| U01.06 | Output frequency of the former one fault | 0.00～Fup | 0.00Hz | ⊙ |

| | | | | |
|---|---|---|---|---|
| U01.07 | Output current of the former one fault | 0.0～3000.0A | 0.0A | ⊙ |
| U01.08 | Bus Voltage of the former one fault | 0～1200V | 0V | ⊙ |
| U01.09 | Cumulative runtime of the former one fault | 0～65535h | 0h | ⊙ |
| U01.10 | Former two fault categories | Like the latest one fault record | Err00 | ⊙ |
| U01.11 | Output frequency of the former two faults | 0.00～Fup | 0.00Hz | ⊙ |
| U01.12 | Output current of the former two faults | 0.0～3000.0A | 0.0A | ⊙ |
| U01.13 | Bus Voltage of the former two faults | 0～1200V | 0V | ⊙ |
| U01.14 | Cumulative runtime of the former two faults | 0～65535h | 0h | ⊙ |
| U01.15 | Previous 3 categories of faults | The same with U01.00 | Err00 | ⊙ |
| U01.16 | Previous 4 categories of faults | The same with U01.00 | Err00 | ⊙ |
| U01.17 | Previous 5 categories of faults | The same with U01.00 | Err00 | ⊙ |
| U01.18 | Previous 6 categories of faults | The same with U01.00 | Err00 | ⊙ |
| U01.19 | Previous 7 categories of faults | The same with U01.00 | Err00 | ⊙ |
| U01.20 | Previous 8 categories of faults | The same with U01.00 | Err00 | ⊙ |
| U01.21 | Previous 9 categories of faults | The same with U01.00 | Err00 | ⊙ |
| **H00 Group: PV Pump Special Set** | | | | |
| H00.00 | Pump Machine Control | 0:Null<br>1:Valid | 1 | × |
| H00.01 | Selection of Inverter Power | 0:Mains<br>1:Solar Panel | 1 | × |
| H00.02 | Vmpp Selection of Voltage Given Mode | 0:CVT (Constant Voltage appr Given)<br>1:Tracking of Max Power Point (MPPT)<br>2:Automatic MPPT<br>3:Fast MPPT<br>4:Quick start MPPT | 3 | × |
| H00.03 | Vmpp voltage CVT setting | 0～750V | 540V | △ |
| H00.04 | Mini voltage reference of MPPT | 0～Max Voltage | 500V | × |
| H00.05 | Max voltage reference of MPPT | Max Voltage～750V | 600V | × |
| H00.06 | PID Filter Time Given | 0.000～10.000s | 0.000s | △ |
| H00.07 | PID Filter Time Feedback | 0.000～10.000s | 0.000s | △ |
| H00.08 | PID Filter Time Output | 0.000～10.000s | 0.000s | △ |
| H00.09 | Ratio Gain Kp1 | 0.00～100.00 | 0.10 | △ |
| H00.10 | Points Time KI | 0.00～100.00 | 0.10 | △ |
| H00.11 | PID Upper Limit of Output Frequency | PID Lower Limit of Output Frequency～100.0%（100.0% corresponds to the max frequency） | 100.0% | × |
| H00.12 | PID Lower Limit of Output | 0.0%～PID Upper Limit of Output | 20.0% | × |

| | Frequency | Frequency | | |
|---|---|---|---|---|
| H00.13 | Dormant Delay Time of Weak light Pre-warning | 0.0～6000.0s | 600.0s | △ |
| H00.14 | Wake-up Delay Time of Weak Light | 0.0～6000.0s | 100.0s | △ |
| H00.15 | Feedback Channel Selection of Reservoir Water Level | 0:Null<br>1:AI1<br>2:AI2<br>3:AI3 | 0 | × |
| H00.16 | Clean up the delay time of full-water pre-warning | 0～10000s | 600s | △ |
| H00.17 | Threshold of reservoir water level | 0.0～100.0 | 25.0% | △ |
| H00.18 | Dormant Delay Time of Overtank Pre-warning | 0～10000s | 60s | △ |
| H00.19 | Detection of reservoir hydraulic probe | 0.0～100.0 | 100.0% | △ |
| H00.20 | Pre-warning delay time of pump under-load | 0.0～1000.0s | 60.0s | △ |
| H00.21 | Pre-warning current level of pump under-load | 0.0～100.0% 0.0:Null | 0.0% | △ |
| H00.22 | Reset delay time of pump under-load | 0.0～1000.0s | 60.0s | △ |
| H00.23 | Threshold of lag-frequency | 0.00～200.00Hz | 0.30Hz | △ |
| H00.24 | Water level direction detection | 0:Positive direction，higher detection value higher water level<br>1:Negative position，higher detection value lower water level | 1 | × |
| H00.25 | Weak light voltage | 80V～MPPT minimum voltage(220V inverter)<br>230V～MPPT minimum voltage(380V inverter) | 80V<br>230V | × |
| H00.26 | Frequency given mode | 0: Maximum frequency<br>1: Master frequency given mode | 0 | × |
| H00.31 | Pump rated flow $Q_N$ | 0.0～1000.0 m3/h | 6.0 m3/h | △ |
| H00.32 | Pump rated head $H_N$ | 0.0～500.0m | 24m | △ |
| H00.33 | Pump cumulative flow zero clearing | 0: Invalid<br>1: Valid | 0 | △ |
| H00.34 | Pump current flow | $Q = Q_N * f / f_N$ (m3/h) | 0.0 m3/h | ⊙ |
| H00.35 | Pump current head | $H = 0.9H_N * (f / f_N)^2$ (m) | 0.0 m | ⊙ |
| H00.36 | Pump cumulative flow | Unit: m3 | 0 m3 | ⊙ |
| H00.38 | Start Freq for Quick start MPPT Mode | 0.00～50.00Hz | 20.00Hz | × |

## 5.2 H00 Group: Detailed Explanation of Function Code

| | | | | |
|---|---|---|---|---|
| H00.00 | Pump Machine Control | 0:Null<br>1:Valid | 1 | × |

< 0: null >
For standard model
< 1:Valid >
For PV pumps special inverter，H00 Group: Invalid

| | | | | |
|---|---|---|---|---|
| H00.01 | Selection of Inverter Power | 0:Mains<br>1:Solar Panel | 1 | × |

< 0: Mains >
Inverter power supply through the grid, frequency given refer to group of F01, HOO.02～H00.12 invalid.
< 1: PV Panels >
Inverter power supply through solar panels, frequency given mainly through tracking and adjusting the max power-point PI of solar panels to get.For more details, please refer to H00.02～H00.12.

| | | | | |
|---|---|---|---|---|
| H00.02 | Vmpp Selection of Voltage Given Mode | 0:CVT<br>( Constant Voltage appr Given )<br>1:Tracking of Max Power Point (MPPT)<br>2:Automatic MPPT<br>3:Fast MPPT<br>4:Quick start MPPT | 2 | × |

< 0: CVT (Constant Voltage appr Given) >
Adopt voltage given mode; reference voltage is a fixed value, given by H00.03.

< 1: Max power point tracking（MPPT）>
Using max power point tracking the given reference voltage, the reference voltage will not stop changing until the system stable，the maximum power point of this searching mode is limited by range of H00.04 and H00.05

< 2: Automatic MPPT >
System track the maximum power point automatically, adaptive to different solar panel, can track and get maximum power point rapidly.
No matter which reference voltage mode adopted, when bus voltage higher than reference voltage, the target frequency will change to upper limit of PI output frequency; when bus voltage lower than reference voltage, target frequency will change to lower limit of PI output frequency.

< 3: Fast MPPT >
System fast track the maximum power point automatically, adaptive to different solar panel, can track and get maximum power point rapidly.
No matter which reference voltage mode adopted, when bus voltage higher than reference voltage, the target frequency will change to upper limit of PI output frequency; when bus voltage lower than reference voltage, target frequency will change to lower limit of PI output frequency.

< 4:Quick start MPPT >
This mode is based on mode 3(Fast MPPT), in addition to, adding quick start frequency(H00.38).

| | | | | |
|---|---|---|---|---|
| H00.03 | Vmpp voltage CVT setting | 0～750V | 540V | △ |

When H00.02 is zero, reference voltage will be given by this function code.

| | | | | |
|---|---|---|---|---|
| H00.04 | MPPT mini voltage reference | 0～Max Voltage | 500V | × |
| H00.05 | MPPT max voltage reference | Max Voltage～750V | 600V | × |

When H00.03 is 1, MPPT voltage will track within H00.04~H00.05, H00.05 must be larger than H00.04, the smaller the difference between them, the narrower the tracking range, tracking will be faster. But the voltage point of max power must fall in this range.

| | | | | |
|---|---|---|---|---|
| H00.06 | PID Given Filter Time | 0.000～10.000s | 0.000s | △ |
| H00.07 | PID Response Filter Time | 0.000～10.000s | 0.000s | △ |
| H00.08 | PID Output Filter Time | 0.000～10.000s | 0.000s | △ |
| H00.09 | Ratio Gain Kp1 | 0.00～100.00 | 0.10 | △ |
| H00.10 | Points Time KI | 0.00～100.00 | 0.10 | △ |
| H00.11 | PID Upper limit of output frequency | PID Lower limit of output frequency～100.0%（100.0% corresponds to the max frequency） | 100.0% | × |
| H00.12 | PID Lower limit of output frequency | 0.0%～PID Upper limit of output frequency | 20.0% | × |

Refer to F13 group of PID function description in FR200 user manual.

| | | | | |
|---|---|---|---|---|
| H00.13 | Delay time of weak light pre-warning sleep | 0.0～6000.0s | 600.0s | △ |
| H00.14 | Delay time of weak light wake-up | 0.0～6000.0s | 100.0s | △ |

When the output frequency less than or equal with the lower limit of PI output frequency (H00.12), delaying timing begins, continuing this state until delay time of weak light pre-warning (H00.13) arrives, weak-light pre-warning reported (Arn33), and start dormant.

In weak light pre-warning, when output frequency larger than lower limit of PI output frequency, delaying timing begins, and continue this status until arrival delay time （H00.14）of wake-up at weak light, clean the weak light pre-warning, re-enter the running status.

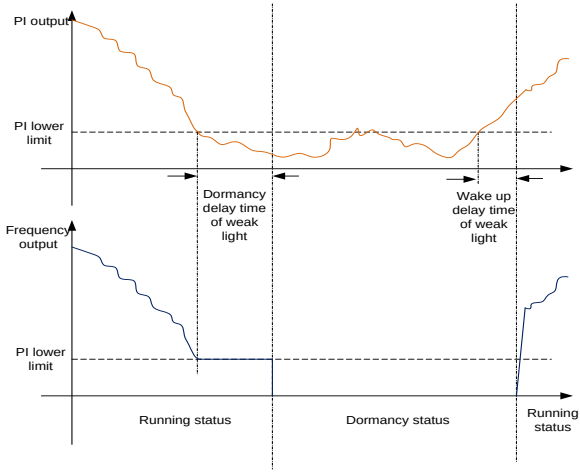


**Figure 3-1 Weak light dormancy & wake up**

| | | | | |
|---|---|---|---|---|
| H00.15 | Feedback channel selection of reservoir water level | 0:Null<br>1:AI1<br>2:AI2<br>3:AI3 | 0 | × |

< 0: Null >
Control of water level is invalid.
< 1: AI1 >
AI1 for analog signal source of water-level control
< 2: AI2 >
AI2 for analog signal source of water-level control
< 3: AI3 >
AI3 for analog signal source of water-level control

| | | | | |
|---|---|---|---|---|
| H00.16 | Clean up the delay time of overtank pre-warning | 0～10000s | 600s | △ |
| H00.17 | Reservoir full of water control | 0.0～100.0 | 25.0% | △ |
| H00.18 | Dormancy delay time of reservoir full of water pre-warning | 0～10000s | 60s | △ |

When the detected water level control analog signal less than water level threshold (H00.17), and continue this status over the delay time of H00.18, reporting the pre-warning of water-full (Arn34), and dormancy.
In water-full pre-warning, when the detected water level control analog signal larger than H00.17, delay timer begins, and continue this status over the delay time of H00.16, clear the full-water pre-warning, recover the normal operation.

| | | | | |
|---|---|---|---|---|
| H00.19 | Detection of reservoir hydraulic probe | 0.0～100.0 | 100.0% | △ |

0.0% means Null.
When not 0.0%, when the detected water level control analog signal larger than H00.19 hydraulic probe damaged point, hydraulic probe fault (Err32) will be reported directly, and stopped.

| | | | | |
|---|---|---|---|---|
| H00.20 | Pre-warning delay time of pump under-load | 0.0～1000.0s | 60.0s | △ |
| H00.21 | Pre-warning current level of pump under-load | 0.0～100.0% 0.0:Null | 0.0% | △ |
| H00.22 | Reset delay time of pump under-load | 0.0～1000.0s | 60.0s | △ |

(H00.21) 0.0%: invalid. When not 0.0%, decided by H00.21 parameter setting, 100% correspondence to ratted current of motor.
When absolute value of the difference between target frequency and slop frequency continues less than or equal with H00.23 lag frequency threshold, if the current value continues less than H00.21 set value, over the H00.20 pump under-load delay time, reporting under-load pre-warning(Arn25).
In under-load pre-warning, delay H00.22 under-load reset time, under-load pre-warning restoration.

| | | | | |
|---|---|---|---|---|
| H00.23 | Lag frequency threshold | 0.00～200.00Hz | 0.30Hz | △ |

Use for adjusting the condition of under-load operation. When absolute value of the difference between target frequency and slop frequency continues less than or equal with lag frequency threshold, current comparison will be required.

| | | | | |
|---|---|---|---|---|
| H00.24 | Water level direction detection | 0:Positive direction，higher detection value higher water level<br>1:Negative position，higher detection value lower water level | 1 | × |

To set the relationship between hydraulic probe detected signal and water level
< 0: Positive direction, higher detection value higher water level >
< 1: Negative position, higher detection value lower water level >

| | | | | |
|---|---|---|---|---|
| H00.25 | Weak light voltage | 230V～MPPT minimum voltage | 230V | × |

For inverters with 380V, range: 230V～MPPT minimum voltage Default Value:230V
For inverters with 220V, range: 80V～MPPT minimum voltage Default Value:80V
When bus voltage is lower than the value of weak light voltage, inverter will soon entry the statue of weak light.

| | | | | |
|---|---|---|---|---|
| H00.26 | Frequency given mode | 0: Maximum frequency<br>1: Master frequency given mode | 0 | × |

< 0:Maximum frequency >
Given frequency is the maximum frequency adjusted by MPPT function
<1:Master frequency given mode>
In frequency range adjusted by MPPT function, given frequency is adjusted by F01.01

| | | | | |
|---|---|---|---|---|
| H00.31 | Pump rated flow $Q_N$ | 0.0～1000.0 m3/h | 6.0 m3/h | △ |
| H00.32 | Pump rated head $H_N$ | 0.0～500.0m | 24m | △ |
| H00.33 | Pump cumulative flow zero clearing | 0: Invalid<br>1: Valid | 0 | △ |
| H00.34 | Pump current flow | $Q = Q_N * f / f_N$ (m3/h) | 0.0 m3/h | ⊙ |
| H00.35 | Pump current head | $H = 0.9H_N * (f / f_N)^2$ (m) | 0.0 m | ⊙ |
| H00.36 | Pump cumulative flow | Unit: m3 | 0 m3 | ⊙ |

This group parameter is used to estimate the pump flow and head during operation. To set pump rated flow (H00.31) and pump rated head (H00.32), inverter will automatically estimate the pump current flow and current head according to the operation state, and pump cumulative flow (H00.36) will be recorded. Parameter H00.33 is the function of pump cumulative flow zero clearing and recalculate.

| | | | | |
|---|---|---|---|---|
| H00.38 | Start Freq for Quick start MPPT Mode | 0.00～50.00Hz | 20.00Hz | × |

This is valid only when H00.02=4(Quick start MPPT mode). Used to speed up starting.

# Chapter 6 Troubleshooting and Countermeasures

PV580 inverters supply many kinds of warning information and protection functions, when failure occurred, function of protection actives, inverters will stop output, fault relay contact of inverter active, and display the fault code on inverter operation panel. Before asking support, users can self-check according to this chapter tips, and analyze the fault reasons, get the solutions. If fault still can't be solved, please ask for service, contact with agents or directly to FRECON

| Operator Panel Displays | Fault Name | Fault Reasons | Troubleshooting |
|---|---|---|---|
| Err01 | Acceleration Over-current | 1. Inverter output circuit grounding or shorted<br>2. Acceleration time is too short<br>3. Manually boost the torque or V/F curve unsuitable<br>4. Voltage is too low<br>5. Start the rotating motor<br>6. Shock load on acceleration<br>7. Inverter selection is too small | 1. Peripheral troubleshooting<br>2. Prolong the acceleration time<br>3. Adjust the V/F curve Or manually-torque-boost<br>4. The voltage adjusted to a normal range<br>5. Select start on rotational-speed tracking or waiting for motor stopped<br>6. Cancel shock-load<br>7. Select inverter with a larger power |
| Err02 | Deceleration Over-current | 1. Inverter output circuit grounding or shorted<br>2. Deceleration time is too short<br>3. Voltage is too low<br>4. Shock load on deceleration<br>5. No installation of braking resistor | 1. Peripheral troubleshooting<br>2. Prolong the deceleration time<br>3. The voltage adjusted to a normal range<br>4. Cancel shock-load<br>5. Install braking resistor |
| Err03 | Constant-speed Over-current | 1. Inverter output circuit grounding or shorted<br>2. Voltage is too low<br>3. If there is shock-load during running<br>4. Inverter selection is too small | 1. Peripheral troubleshooting<br>2. The voltage adjusted to a normal range<br>3. Cancel shock-load<br>4. Select inverter with a larger power |
| Err04 | Acceleration Overvoltage | 1. Input voltage is high<br>2. There is an external force during acceleration dragging the motor to work<br>3. Acceleration time is too short<br>4. No installation of braking resistor | 1. The voltage adjusted to a normal range<br>2. Cancel the external power or install braking resistor<br>3. Prolong the acceleration time<br>4. Install braking resistor |
| Err05 | Deceleration Overvoltage | 1. Input voltage is high<br>2. There is an external force during deceleration dragging the motor to work<br>3. Deceleration time is too | 1. The voltage adjusted to a normal range<br>2. Cancel the external power or install braking resistor<br>3. Prolong the deceleration |

| | | | |
|---|---|---|---|
| | | short<br>4. No installation of braking resistor | time<br>4. Install braking resistor |
| Err06 | Constant-speed Overvoltage | 1. Input voltage is too high<br>2. There is an external force during running dragging the motor to work | 1. The voltage adjusted to a normal range<br>2. Cancel the external power or install braking resistor |
| Err07 | Bus Under voltage protection | 1. Momentary power failure<br>2. The inverter input voltage<br>3. Bus voltage abnormal<br>4. Rectifier bridge and buffer resistance are abnormal<br>5. Drive board abnormal<br>6. Control panel abnormal | 1. Reset Failure<br>2. Adjust voltage to normal range<br>3. Ask for technical support<br>4. Ask for technical support<br>5. Ask for technical support<br>6. Ask for technical support |
| Err08 | Short circuit protection | 1. Inverter output circuit shorted<br>2. Acceleration/ Deceleration time is too short<br>3. Wirings between motor and inverter is too long<br>4. Module Overheating<br>5. Internal wirings of inverter loosened<br>6. Main Board Abnormal<br>7. Drive Board Abnormal<br>8. Inverter Module Abnormal | 1. Peripheral troubleshooting<br>2. Prolong the acceleration/deceleration time<br>3. Install the reactor or output-filter<br>4. Check and confirm the air-channel unblocked, fans operation normal<br>5. All cables plugged<br>6. Ask for technical support<br>7. Ask for technical support<br>8. Ask for technical support |
| Err09 | Input Open-phase | 1. Power of three-phase-input is abnormal<br>2. Drive board abnormal<br>3. Lightning board abnormal<br>4. Main board abnormal | 1. Check and solve the problems in peripheral wirings<br>2. Ask for technical support<br>3. Ask for technical support<br>4. Ask for technical support |
| Err10 | Output Open-phase | Lead-wire from inverter to motor is abnormal<br>Three-phase output of inverter is unbalanced during motor-running<br>3. Drive board abnormal<br>4. Inverter Module Abnormal | 1. Peripheral troubleshooting<br>2. Check and confirm the motor three-phase winding to be normal<br>3. Ask for technical support<br>4. Ask for technical support |
| Err11 | Motor Overload | 1. Motor-protection parameters F11.17 set incorrectly<br>2. Load is too large or motor rocked rotor<br>3. Inverter selection is too small | 1. Setting the parameters correctly<br>2. Lowering the load and check the conditions of motor and mechanical<br>3. Select inverter with a larger power |
| Err12 | Inverter Overload | 1. Load is too large or motor rocked rotor<br>2. Inverter selection is too small | 1. Reduce load and check the conditions of motor and mechanical<br>2. Select inverter with a larger power |
| Err13 | Fault protection of external input | 1. Input the external fault signal by multi-function terminal | 1. Reset to run |

| | | | |
|---|---|---|---|
| Err14 | Overheat | 1. Ambient temperature is too high<br>2. Air-channel blocked<br>3. Fans damaged<br>4. Module thermistors damaged<br>5. Inverter module damaged | 1. Lowering the ambient temperature<br>2. Clean up the air-channel<br>3. Replace the fans<br>4. Replace the thermistors<br>5. Replace the inverter module |
| Err15 | Memory Failure | 1. EEPROM Chips damage | 1. Replace the Main Board |
| Err16 | Cancel the self-identification | 1. Press the button of STOP/RST during self-identification | 1. Press STOP/RST for restoration |
| Err17 | Self-identification failure | 1. Motor and the inverter output terminals are not connected<br>2. Motor connects to load<br>3. Motor Failure | 1. Check the wirings between inverter and motor<br>2. Motor breaks away from load<br>3. Check motor |
| Err18 | 485 Communication Timeout | Upper computer works abnormally<br>2. Communication cable is abnormal<br>3. F15 communication parameters set incorrectly | 1. Check the wirings of upper computer<br>2. Check the communication cable<br>3. Set the communication parameters correctly |
| Err19 | PID feedback disconnection on running | 1. PID feedback lower than the value set by F13.24 | 1. Check the PID feedback signal or set F13.24 to be a suitable value |
| Err20 | The running time arrives | 1. Setting the function of running time arrives | 1. Refer to description of F05.14 |
| Err21 | Parameter Upload Error | 1. Copy card uninstalled or plugged unsuitable<br>2. Parameters copy card abnormal<br>3. Control board abnormal | 1. Parameter copy card installed correctly<br>2. Ask for technical support<br>3. Ask for technical support |
| Err22 | Parameter Download Error | 1. Copy card uninstalled or plugged unsuitable<br>2. Parameters copy card abnormal<br>3. Control board abnormal | 1. Parameter copy card installed correctly<br>2. Ask for technical support<br>3. Ask for technical support |
| Err23 | Braking Unit failure | 1. Braking wirings fault or braking tube damaged<br>2. Value of external braking resister is too small | 1.Check the brake unit, and replace the new brake tube<br>2. Increasing the braking resistor |
| Err24 | Disconnection Fault of temperature sensor | 1. Temperature sensor failure or cable break | 1. Ask for technical support |
| Err25 | Inverter loss-load | 1. Running current of inverter is less than F11.22 | 1. Confirm whether the load loss or parameters of F11.22. F11.23 conform to the actual running conditions. |
| Err26 | With-wave current limit fault | 1. Load is too large or motor rocked-rotor<br>2. Inverter selection is too small | 1. Reduce the load or check the conditions of motor or mechanical<br>2. Select the inverter with larger power |
| Err27 | Soft-start relay unclosed | 1. Grid voltage is too low<br>2. Rectifier module failure | 1. Check the grid voltage<br>2. Ask for technical support |

| | | | |
|---|---|---|---|
| Err28 | EEPROM Version Incompatible | 1. Parameter version of up/download module is inconsistent with the one of control panel | 1. Re-upload parameters to up/download modules |
| Err29 | Hardware detect Overcurrent | 1. Acceleration/Deceleration time is too short<br>2. Motor Parameters is Inaccurate<br>3. Hardware failure of Inverter | 1. Prolong the acceleration/deceleration time<br>2. Setting the correct motor parameter<br>3. Ask for technical support |
| Err30 | Hardware detect overvoltage | 1. Deceleration time is too short<br>2. No installation of braking resistors<br>3. Hardware failure of Inverter | 1. Prolong the deceleration time<br>2. Install the braking resistor<br>3. Ask for technical support |
| Err32 | Hydraulic Probe Failure | Hydraulic Probe Failure | Hydraulic Probe Changed |
| A33 | Pre-warning of Weak Light | Output frequency lower than or equal with lower limit of PI output frequency, and continues this status until arrives at delay time of weak light. | Check the lower limit of PI output frequency and weak-light delay theset value |
| A34 | Pre-warning of Full-water | Water-lever feedback lower than the set threshold, and continue to the delay time | Check the pre-warning point of water level |